CS 687 Jana Kosecka

Naïve Bayes

[Some of these slides were created by Dan Klein and Pieter Abbeel for CS188 Intro to AI at UC Berkeley.

Outline

- Uncertainty
- Probability
- Syntax and Semantics
- Inference
- Independence and Bayes' Rule

Naïve Bayes

 Naïve Bayes model (the effects are independent given the cause)

 $\mathbf{P}(Cause, Effect_1, \dots, Effect_n) = \mathbf{P}(Cause) \pi_i \mathbf{P}(Effect_i | Cause)$

- · This simplifying assumption, often works well
- Example SPAM classification

•

Example: Spam Filter

- Input: email
- Output: spam/ham



Dear Sir.

First, I must solicit your confidence in this transaction, this is by virture of its nature as being utterly confidencial and top secret. ...



TO BE REMOVED FROM FUTURE MAILINGS, SIMPLY REPLY TO THIS MESSAGE AND PUT "REMOVE" IN THE SUBJECT.

99 MILLION EMAIL ADDRESSES FOR ONLY \$99



Ok, Iknow this is blatantly OT but I'm beginning to go insane. Had an old Dell Dimension XPS sitting in the corner and decided to put it to use, I know it was working pre being stuck in the corner, but when I plugged it in, hit the power nothing happened.

Slide from Dan Klein

Example: Spam Filter

- Input: email
- Output: spam/ham
- Setup:
 - Get a large collection of example emails, each labeled "spam" or "ham"
 - Note: someone has to hand label all this data!
 - Want to learn to predict labels of new, future emails



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 - Get a large collection of example emails, each labeled "spam" or "ham"
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 - Want to learn to predict labels of new, future emails
- Features: The attributes used to make the ham / spam decision



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Slide from Dan Klein

Example: Spam Filter

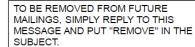
- Input: email
- Output: spam/ham
- Setup:
 - Get a large collection of example emails, each labeled "spam" or "ham"
 - Note: someone has to hand label all this data!
 - Want to learn to predict labels of new, future emails
- Features: The attributes used to make the ham / spam decision
 - Words: FREE!
 - Text Patterns: \$dd, CAPS
 - Non-text: SenderInContacts

. . . .



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Slide from Dan Klein



Model-Based Classification

- · Model-based approach
 - Build a model (e.g. Bayes' net) where both the output label and input features are random variables
 - Instantiate any observed features
 - Query for the distribution of the label conditioned on the features
- Challenges
 - What structure should the BN have?
 - How should we learn its parameters?



Naïve Bayes for Digits

- Naïve Bayes: Assume all features are independent effects of the label
- Simple digit recognition version:
 - One feature (variable) F_{ij} for each grid position <i,j>
 - Feature values are on / off, based on whether intensity is more or less than 0.5 in underlying image
 - Each input maps to a feature vector, e.g.



- Here: lots of features, each is binary valued
- Naïve Bayes model: $P(Y|F_{0,0}...F_{15,15}) \propto P(Y) \prod_{i,j} P(F_{i,j}|Y)$
- What do we need to learns

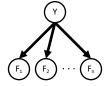
General Naïve Bayes

A general Naive Bayes model:

|Y| parameters

$$P(Y, F_1 ... F_n) = P(Y) \prod_i P(F_i | Y)$$

|Y| x |F|n values



- We only have to specify how each feature depends on the class
- Total number of parameters is *linear* in n
- Model is very simplistic, but often works anyway

Inference for Naïve Bayes

- Goal: compute posterior distribution over label variable Y
 - Step 1: get joint probability of label and evidence for each label

$$P(Y, f_{1} \dots f_{n}) = \begin{bmatrix} P(y_{1}, f_{1} \dots f_{n}) \\ P(y_{2}, f_{1} \dots f_{n}) \\ \vdots \\ P(y_{k}, f_{1} \dots f_{n}) \end{bmatrix} \Longrightarrow \begin{bmatrix} P(y_{1}) \prod_{i} P(f_{i}|y_{1}) \\ P(y_{2}) \prod_{i} P(f_{i}|y_{2}) \\ \vdots \\ P(y_{k}) \prod_{i} P(f_{i}|y_{k}) \end{bmatrix}$$

- Step 2: sum to get probability of evidence
- Step 3: normalize by dividing Step 1 by Step 2

General Naïve Bayes

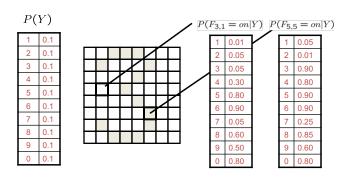
- What do we need in order to use Naïve Bayes?
 - Inference method (we just saw this part)
 - Start with a bunch of probabilities: P(Y) and the $P(F_i|Y)$ tables Use standard inference to compute $P(Y|F_1...F_n)$

 - Nothing new here
 - Estimates of local conditional probability tables
 - P(Y), the prior over labels

 - P(F_i|Y) for each feature (evidence variable)
 These probabilities are collectively called the *parameters* of the model and denoted by

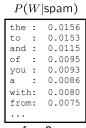
 - Up until now, we assumed these appeared by magic, but...
 ...they typically come from training data counts: we'll look at this soon

Example: Conditional Probabilities



Example: Spam Filtering

- Model: $P(Y, W_1 \dots W_n) = P(Y) \prod P(W_i|Y)$
- · What are the parameters?



$$\begin{array}{c|ccc} P(W|\mathsf{ham}) \\ \hline \text{the:} & 0.0210 \\ \text{to:} & 0.0213 \\ \text{of:} & 0.0119 \\ 2002: & 0.0110 \\ \text{with:} & 0.0108 \\ \text{from:} & 0.0107 \\ \text{and:} & 0.0105 \\ \text{a:} & 0.0100 \\ \hline \\ \cdots \\ \end{array}$$

· Where do these tables come from?

Spam Example

Word	P(w spam)	P(w ham)	Tot Spam	Tot Ham
(prior)	0.33333	0.66666	-1.1	-0.4

P(spam | w) = 98.9

Training and Testing





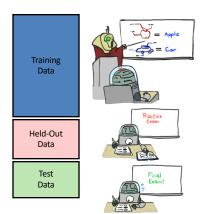


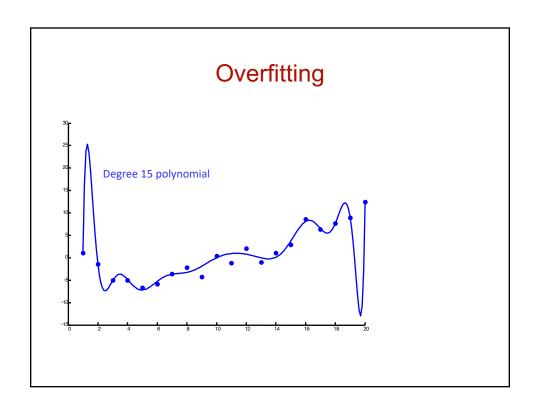
Empirical Risk Minimization

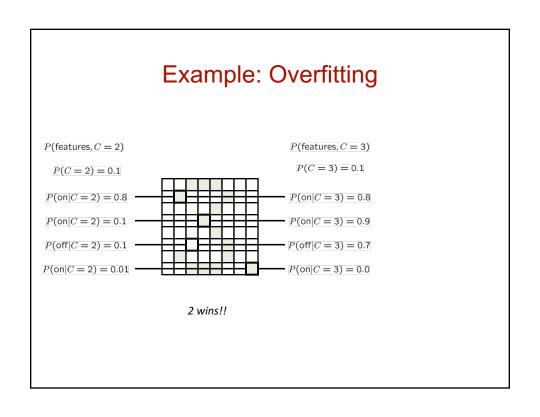
- Empirical risk minimization
 - Basic principle of machine learning
 - We want the model (classifier, etc) that does best on the true test distribution
 - Don't know the true distribution so pick the best model on our actual training set
 - Finding "the best" model on the training set is phrased as an optimization problem
- Main worry: overfitting to the training set
 - Better with more training data (less sampling variance, training more like test)
 - Better if we limit the complexity of our hypotheses (regularization and/or small hypothesis spaces)

Important Concepts

- Data: labeled instances (e.g. emails marked spam/ham)
 - Training set
 - Held out set
 - Test set
- Features: attribute-value pairs which characterize each x
- · Experimentation cycle
 - Learn parameters (e.g. model probabilities) on training set
 - (Tune hyperparameters on held-out set)
 - Compute accuracy of test set
 - Very important: never "peek" at the test set!
- Evaluation (many metrics possible, e.g. accuracy)
 - Accuracy: fraction of instances predicted correctly
- Overfitting and generalization
 - Want a classifier which does well on test data
 - Overfitting: fitting the training data very closely, but not generalizing well
 - We'll investigate overfitting and generalization formally in a few lectures







Example: Overfitting

Posteriors determined by relative probabilities (odds ratios):

 $\overline{P(W|\text{spam})}$ south-west: inf nation: inf morally: inf nicely: inf extent: inf seriously: inf ...

P(W|ham)

What went wrong here?

 $rac{P(W|\mathsf{spam})}{P(W|\mathsf{ham})}$

screens : inf minute : inf guaranteed : inf \$205.00 : inf delivery inf signature : inf ...

Generalization and Overfitting

- Relative frequency parameters will overfit the training data!
 - Just because we never saw a 3 with pixel (15,15) on during training doesn't mean we won't see
 it at test time
 - Unlikely that every occurrence of "minute" is 100% spam
 - Unlikely that every occurrence of "seriously" is 100% ham
 - What about all the words that don't occur in the training set at all?
 - In general, we can't go around giving unseen events zero probability
- As an extreme case, imagine using the entire email as the only feature (e.g. document ID)
 - Would get the training data perfect (if deterministic labeling)
 - Wouldn't generalize at all
 - Just making the bag-of-words assumption gives us some generalization, but isn't enough
- To generalize better: we need to smooth or regularize the estimates

Parameter Estimation

- · Estimating the distribution of a random variable
- Elicitation: ask a human (why is this hard?)



- Empirically: use training data (learning!)
 - E.g.: for each outcome x, look at the *empirical rate* of that value:

$$P_{\mathsf{ML}}(x) = \frac{\mathsf{count}(x)}{\mathsf{total \; samples}}$$





$$P_{\mathsf{ML}}(\mathbf{r}) = 2/3$$

This is the estimate that maximizes the likelihood of the data

$$L(x,\theta) = \prod_{i} P_{\theta}(x_i)$$

Maximum Likelihood?

· Relative frequencies are the maximum likelihood estimates

$$\begin{array}{l} \theta_{ML} = \arg\max_{\theta} P(\mathbf{X}|\theta) \\ = \arg\max_{\theta} \prod_{i} P_{\theta}(X_{i}) \end{array} \implies P_{\mathsf{ML}}(x) = \frac{\mathsf{count}(x)}{\mathsf{total samples}} \\ \end{array}$$

Another option is to consider the most likely parameter value given the data

$$\begin{split} \theta_{MAP} &= \arg\max_{\theta} P(\theta|\mathbf{X}) \\ &= \arg\max_{\theta} P(\mathbf{X}|\theta) P(\theta) / P(\mathbf{X}) \end{split}$$
 ?????
$$&= \arg\max_{\theta} P(\mathbf{X}|\theta) P(\theta)$$

Laplace Smoothing

- · Laplace's estimate:
 - Pretend you saw every outcome once more than you actually did

 $P_{LAP}(X) =$





$$P_{LAP}(x) = \frac{c(x) + 1}{\sum_{x} [c(x) + 1]}$$

$$C_x[c(x)+1] P_{ML}(X) =$$

$$=\frac{c(x)+1}{N+|X|}$$

 Can derive this estimate with Dirichlet priors (see cs281a)

Laplace Smoothing

- Laplace's estimate (extended):
 - Pretend you saw every outcome k extra times

$$P_{LAP,k}(x) = \frac{c(x) + k}{N + k|X|}$$

- What's Laplace with k = 0?
- k is the strength of the prior
- Laplace for conditionals:
 - Smooth each condition independently:

$$P_{LAP,k}(x|y) = \frac{c(x,y) + k}{c(y) + k|X|}$$







$$P_{LAP,0}(X) =$$

$$P_{LAP,1}(X) =$$

$$P_{LAP,100}(X) =$$

Estimation: Linear Interpolation*

- In practice, Laplace often performs poorly for P(X|Y):

 When |X| is very large

 When |Y| is very large
- Another option: linear interpolation
 Also get the empirical P(X) from the data
 Make sure the estimate of P(X|Y) isn't too different from the empirical P(X)

$$P_{LIN}(x|y) = \alpha \hat{P}(x|y) + (1.0 - \alpha)\hat{P}(x)$$

- What if α is 0? 1?
- For even better ways to estimate parameters see machine learning class

Real NB: Smoothing

- For real classification problems, smoothing is critical
- New odds ratios:

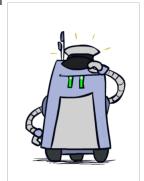
$\overline{P(W \text{spam})}$
, , ,

helvetica	:	11.4
seems	:	10.8
group	:	10.2
ago	:	8.4
areas	:	8.3

P(W|spam) $P(W|\mathsf{ham})$

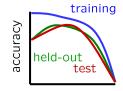
verdana	:	28.8
Credit	:	28.4
ORDER	:	27.2
	:	26.9
money	:	26.5

Do these make more sense?



Tuning on Held-Out Data

- Now we've got two kinds of unknowns
 - Parameters: the probabilities P(X|Y), P(Y)
 - Hyperparameters: e.g. the amount / type of smoothing to do, k, α
- What should we learn where?
 - Learn parameters from training data
 - Tune hyperparameters on different dataWhy?
 - For each value of the hyperparameters, train and test on the held-out data
 - Choose the best value and do a final test on the test data









Errors, and What to Do

· Examples of errors

Dear GlobalSCAPE Customer,

GlobalSCAPE has partnered with ScanSoft to offer you the latest version of OmniPage Pro, for just \$99.99* - the regular list price is \$499! The most common question we've received about this offer is - Is this genuine? We would like to assure you that this offer is authorized by ScanSoft, is genuine and valid. You can get the . . .

. . . To receive your \$30 Amazon.com promotional certificate, click through to

http://www.amazon.com/apparel

and see the prominent link for the \$30 offer. All details are there. We hope you enjoyed receiving this message. However, if you'd rather not receive future e-mails announcing new store launches, please click . . .

What to Do About Errors?

- Need more features—words aren't enough!
 - Have you emailed the sender before?
 - Have 1K other people just gotten the same email?
 - Is the sending information consistent?
 - Is the email in ALL CAPS?
 - Do inline URLs point where they say they point?
 - Does the email address you by (your) name?
- Can add these information sources as new variables in the NB model
- Next class we'll talk about classifiers which let you easily add arbitrary features more easily, and, later, how to induce new features

Baselines

- First step: get a baseline
 - Baselines are very simple "straw man" procedures
 - Help determine how hard the task is
 - Help know what a "good" accuracy is
- Weak baseline: most frequent label classifier
 - Gives all test instances whatever label was most common in the training set
 E.g. for spam filtering, might label everything as ham

 - Accuracy might be very high if the problem is skewed
 E.g. calling everything "ham" gets 66%, so a classifier that gets 70% isn't very good...
- For real research, usually use previous work as a (strong) baseline

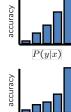
Confidences from a Classifier

- The confidence of a probabilistic classifier:

 Posterior probability of the top label

$$confidence(x) = \max_{y} P(y|x)$$

- Represents how sure the classifier is of the classification Any probabilistic model will have confidences
- No guarantee confidence is correct
- Calibration
 - Weak calibration: higher confidences mean higher accuracy
 - Strong calibration: confidence predicts accuracy rate What's the value of calibration?





Summary

- Bayes rule lets us do diagnostic queries with causal probabilities
- The naïve Bayes assumption takes all features to be independent given the class label
- We can build classifiers out of a naïve Bayes model using training data
- Smoothing estimates is important in real systems
- Classifier confidences are useful, when you can get them