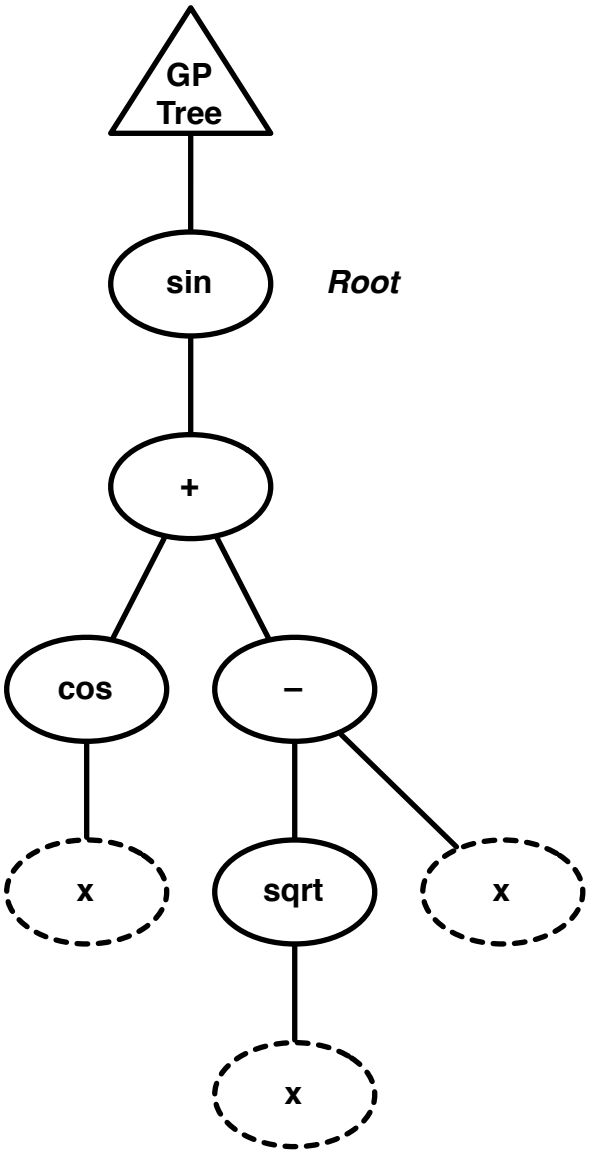
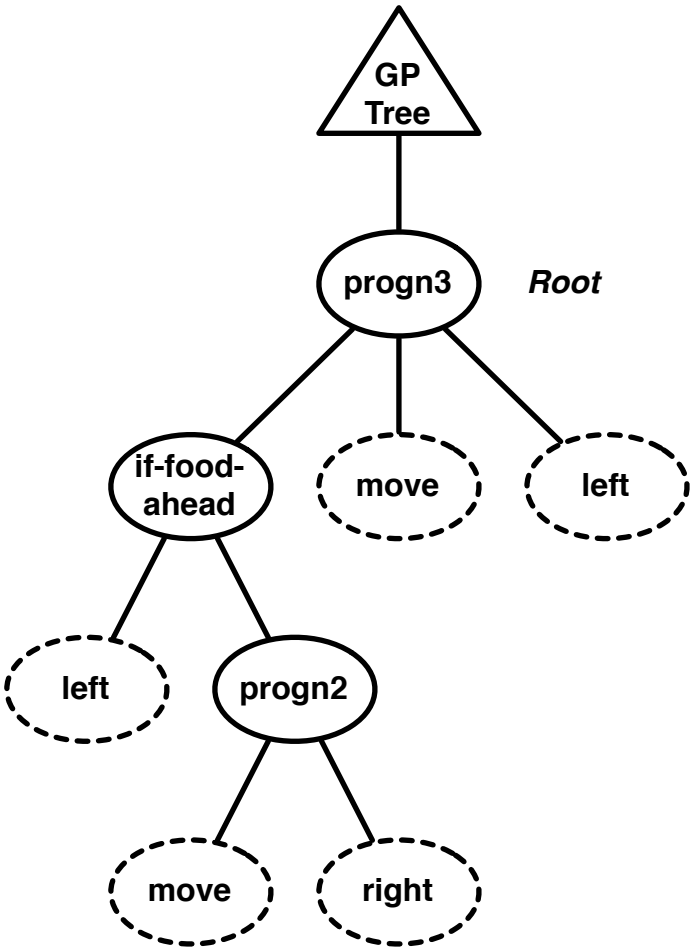

GP
Tree
sin
Root
+
cos
–
x
sqrt
x
x


GP
Tree
progn3
Root
if-food-
ahead
move
left
left
progn2
move
right