# CS483 Analysis of Algorithms <br> Lecture 07 - Dynamic Programming 01 * 

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## Dynamic Programming

Dynamic Programming A Toy Example: Fibonacci number (again)
Shortest path in DAGs Longest increasing subsequences
Binomial Coefficient Binomial Coefficient
Knapsack Problem
Knapsack Problem
Knapsack Problem and Memory Functions Summary
$\square$ A term coined by Richard Bellman in the 1940s

(Image from ieee.org. Richard Bellman, 1920-1984)
$\square$ Some problems solved by dynamic programming

- Longest increasing subsequences
- Fibonacci number
- Knapsack problem
- All-pairs shortest path problem (Floyd's algorithm)
- Optimal binary search tree problem
- Multiplying a sequence of matrices
- String matching (or DNA sequence matching), where we search for the string closest to the pattern
- Convex decomposition of polygons
- ...


## A Toy Example: Fibonacci number (again)

Dynamic Programming A Toy Example: Fibonacci number $D$ (again)
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Summary
$\square \quad f(n)=f(n-1)+f(n-2), f(0)=1, f(1)=1$
$\square$ Recursive brute force approach:
$\square$ DP approach:
$\square \quad$ What's the difference?
$\square \quad$ What's the difference between divide-n-conquer and dynamic programming?

## Shortest path in DAGs

Dynamic Programming A Toy Example: Fibonacci number (again)
$D$ Shortest path in DAGs
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$\square$ Example:

$\square$ Algorithm

Algorithm 0.1: DAG-SHORTEST-PATH $(G, s)$

## Longest increasing subsequences

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Knapsack Problem and Memory Functions Summary
$\square$ Given a sequence of integers, find the longest increasing sequence.
$\square$ Example 1: 5, 2, 8, 6, 3, 6, 9, 7 (the longest increasing subsequences is: $2,3,6,9$ )
$\square$ How do we solve this problem using dynamic programming?
$\square$ Key observation: Convert the numbers into a DAG!
$\square$ Example 2: 3, 5, 1, 3, 11, 19, 4, 17, 21, 9, 13, 18
$\square$ Algorithm
Algorithm 0.2: LIS $(A)$

## Binomial Coefficient

Dynamic Programming A Toy Example: Fibonacci number (again)
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$\downarrow$ Binomial Coefficient
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Summary
$\square \quad(x+y)^{n}=C(n, 0) x^{n}+\cdots+C(n, k) x^{n-k} y^{k}+\cdots+C(n, n) y^{n}$
$\square$ Now, our problem is how to compute $C(n, k)$ for all $k=0 \cdots n$ efficiently
$\square$ We know that $C(n, k)=\frac{n!}{k!(n-k)!}$, which is the combination size of picking $k$ elements from $n$ elements.
$\square \quad$ Brute force algorithm: Compute $C(n, 0), C(n, 1), C(n, 2), \cdots C(n, n)$ individually
$\square$ But we know that the same computations are repeated many times!
$\square \quad$ In fact, we know that $C(n, k)=C(n-1, k-1)+C(n-1, k)$
$\square$ This idea has been discovered many many years ago in China, India, Iran, and Italy, etc, but one of its most famous names is Pascal's Triangle named after Blaise Pascal, a french mathematician

(image of Blaise Pascal 1623-1662)

## Binomial Coefficient

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B Binomial Coefficient
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$\square$ Example: $C(7, k), k=0, \cdots, 7$

|  | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
| :---: | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 0 |  |  |  |  |  |  |  |  |
| 1 |  |  |  |  |  |  |  |  |
| 2 |  |  |  |  |  |  |  |  |
| 3 |  |  |  |  |  |  |  |  |
| 4 |  |  |  |  |  |  |  |  |
| 5 |  |  |  |  |  |  |  |  |
| 6 |  |  |  |  |  |  |  |  |
| 7 |  |  |  |  |  |  |  |  |

$\square \quad$ Algorithm

## Algorithm 0.3: BINOMIAL( $n$ )

$\square \quad$ Time complexity

## Knapsack Problem

Dynamic Programming A Toy Example: Fibonacci number (again)
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$\square \quad$ Knapsack Problem: Given $n$ objects, each object has weight $w$ and value $v$, and a knapsack of capacity $W$, find most valuable items that fit into the knapsack

$\square$ Brute force approach

- generate a list of all potential solutions
- evaluate potential solutions one by one
- when search ends, announce the solution(s) found
$\square \quad$ What is the time complexity of the brute force algorithm?


## Knapsack Problem

Dynamic Programming A Toy Example: Fibonacci number (again)

Shortest path in DAGs Longest increasing subsequences

Binomial Coefficient
Binomial Coefficient
Knapsack Problem

- Knapsack Problem Knapsack Problem and Memory Functions Summary
$\square$ Dynamic programming approach
- Assume that we want to compute the optimal solution $S(w, i)$ for capacity $w<W$ with $i$ items
- Assume that we know the optimal solutions $S\left(w^{\prime}, i^{\prime}\right)$ for all $w^{\prime} \leq w$ and $i^{\prime} \leq i$
- Option 1: Don't add the $k$-th item to the bag, then $S(w, i)=S(w, i-1)$
- Option 2: Add the $k$-the item to the bag, then
$S(w, i)=S\left(w-w_{i}, i-1\right)+v_{i}$

| $w$ | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $12 \mathrm{~kg}, \$ 4$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $1 \mathrm{~kg}, \$ 2$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $2 \mathrm{~kg}, \$ 2$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $1 \mathrm{~kg}, \$ 1$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $4 \mathrm{~kg}, \$ 10$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

$\square \quad$ Time complexity?

## Knapsack Problem and Memory Functions

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$\square$ So far, we look at four DP-based algorithms, all of them are bottom-up approaches.
$\square$ We can in fact design DP-based algorithms using top-down (recursive) approach.

- One important benefit of top-down approach is that we can avoid solving unnecessary subproblems

| $w$ | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $12 \mathrm{~kg}, \$ 4$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $1 \mathrm{~kg}, \$ 2$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $2 \mathrm{~kg}, \$ 2$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $1 \mathrm{~kg}, \$ 1$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $4 \mathrm{~kg}, \$ 10$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

$\square$ Algorithm

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Algorithm 0.4: \(\operatorname{NAPSK}(w, i)\)
```

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```
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if \(V[w, i]<0\)
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if \(V[w, i]<0\)
    then \(\left\{\begin{array}{l}\text { if } w<W[i] \\ \text { then } \text { value } \leftarrow \operatorname{NAPSK}(w, i-1) \\ \text { else } w<W[i] \\ \text { then value } \leftarrow \max \{\operatorname{NAPSK}(w, i-1), \operatorname{NAPSK}(w-W[i], i-1)+V[i]\} \\ V[w, i] \leftarrow \text { value }\end{array}\right.\)
    then \(\left\{\begin{array}{l}\text { if } w<W[i] \\ \text { then } \text { value } \leftarrow \operatorname{NAPSK}(w, i-1) \\ \text { else } w<W[i] \\ \text { then value } \leftarrow \max \{\operatorname{NAPSK}(w, i-1), \operatorname{NAPSK}(w-W[i], i-1)+V[i]\} \\ V[w, i] \leftarrow \text { value }\end{array}\right.\)
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return \((V[w, i])\)
```

return $(V[w, i])$

```
return \((V[w, i])\)
```


## Summary

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$\triangleright$ Summary
$\square \quad$ Things you need to know about dynamic programming (dp)

- programming in dp (and linear programming) is a mathematical term, which means optimization or planning, i.e. it should not be confused with "computer programming" or "programming language"
- dp solves problems with overlapping sub-problems
- dp solves problems which have optimal substructure, i.e., its optimal solution can be constructed from optimal solutions of its sub-problems
- dp stores the results of sub-problems for later reuse
- dp works by converting a problem into a set of sub-problems and representing these sub-problems as a DAG.
$\square$ Next week: Dynamic Programming 2
- Edit distance (string matching)
- Chain matrix multiplication
- All pairs shortest distance


[^0]:    *this lecture note is based on Algorithms by S. Dasgupta, C.H. Papadimitriou, and U.V. Vazirani and Introduction to the Design and Analysis of Algorithms by Anany Levitin.

