
CS483 Analysis of Algorithms

Lecture 08 – Dynamic Programming 02 *

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*this lecture note is based on *Algorithms* by S. Dasgupta, C.H. Papadimitriou, and U.V. Vazirani and *Introduction to the Design and Analysis of Algorithms* by Anany Levitin.

Edit Distance

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- **Observation:** Given two strings $x[1 \dots n]$ and $y[1 \dots m]$. No matter how we match x to y , at the end of the match, we can only have:
 - $x[n]$ matches to $y[m]$
 - $x[n]$ matches to empty
 - $y[m]$ matches to empty
 - **Question:** Is it possible $x[n]$ matches to $y[i < m]$? or $y[m]$ matches to $x[j < n]$?

- **Example:** EXPONENTIAL vs. POLYNOMIAL
 - What are possible endings?

 - What are the subproblems we should consider?

 - How do we get an optimal answer?

Edit Distance

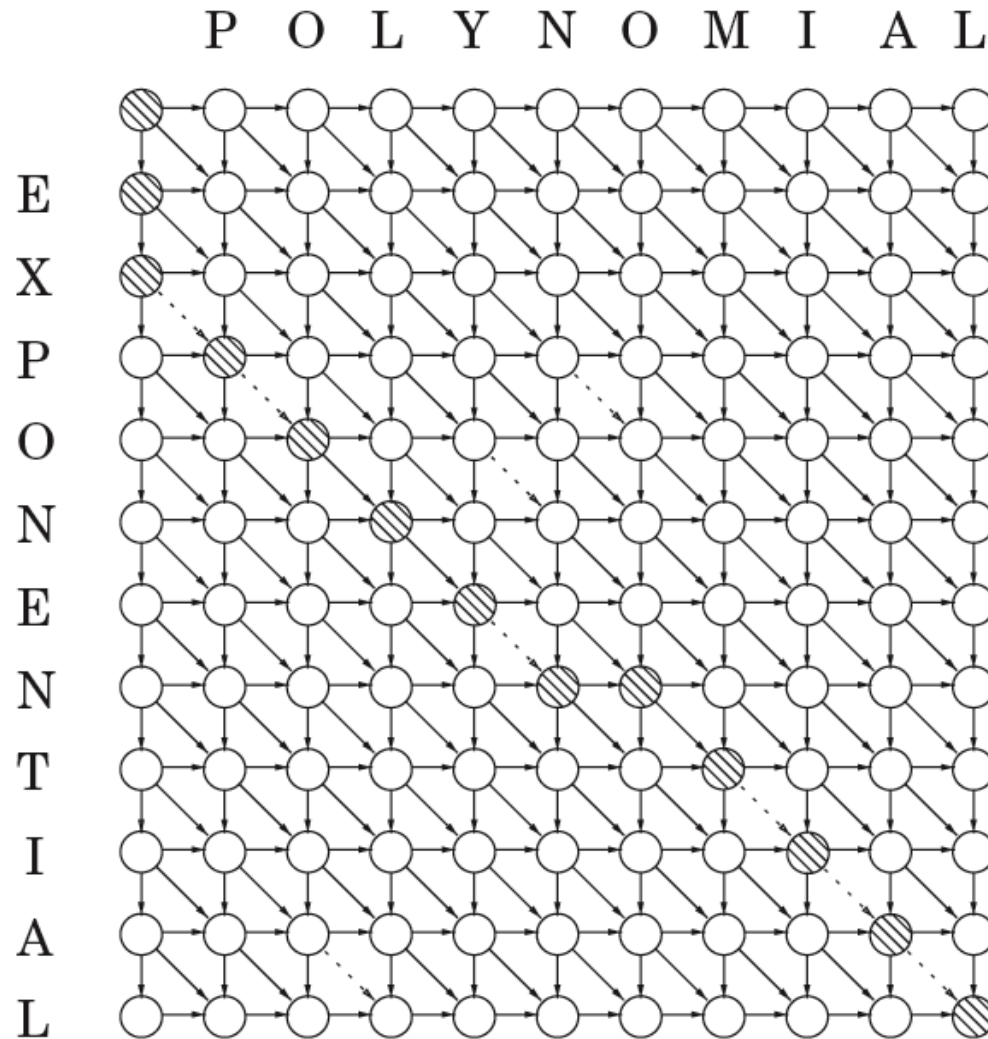
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- Let $E(i, j)$ be the edit distance for the subproblem of strings with lengths i and j
- $E(i, j) = \min\{E(i-1, j-1) + \text{diff}(x[i], y[j]), E(i-1, j) + 1, E(i, j-1) + 1\}$

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Edit Distance and DAG

- Representing the problem as a DAG



Chain Matrix Multiplication

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- Given four matrices, $A[50 \times 20]$, $B[20 \times 1]$, $C[1 \times 10]$, $D[10 \times 100]$, we wish to compute $A \times B \times C \times D$.
- If we compute $((A \times B) \times C) \times D$, we will perform x multiplications?
- What about $((A \times B) \times (C \times D))$?
- How do we find the best way to group matrices so that the number of multiplications is minimized?
 - Brute force
 - Greedy algorithm
 - Dynamic programming

Chain Matrix Multiplication

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- Dynamic programming and DAG
 1. A pair of parentheses groups two matrices
 2. The final matrix represents the root
 3. Example: $((A \times B) \times C) \times D$ and $((A \times B) \times (C \times D))$

- So, our goal is to build an optimal binary tree
- Given four matrices, $A[50 \times 20]$, $B[20 \times 1]$, $C[1 \times 10]$, $D[10 \times 100]$, we wish to compute $A \times B \times C \times D$.
 1. Subproblems with two matrices:
 2. Subproblems with three matrices:
 3. Subproblems with four matrices:

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- General cases: Give a list of matrices $\{A_i\}$, $C(i, j)$ be the minimum cost of $A_i \times \dots \times A_j$, then

$$C(i, j) = \min_{i \leq k < j} \{C(i, k) + C(k + 1, j) + m_{i-1} \cdot m_k \cdot m_j\}$$

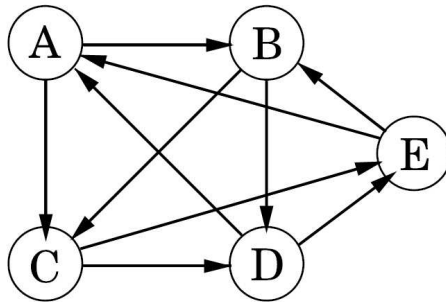
- Example: $A[50 \times 20]$, $B[20 \times 1]$, $C[1 \times 10]$, $D[10 \times 100]$

0	$j = 1$	$j = 2$	$j = 3$	$j = 4$	$j = 5$
$i = 1$					
$i = 2$					
$i = 3$					
$i = 4$					
$i = 5$					

Transitive closure

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- Transitive closure of a graph is a set of vertex pairs of a graph, which can be connected by one or multiple paths
- We can represent the transitive closure using a matrix A . The element $A_{i,j}$ is “1” if there are one or multiple paths between vertices i and j .
- Example:



- Can you design a brute force algorithm? What is its time complexity?

Warshall's Algorithm

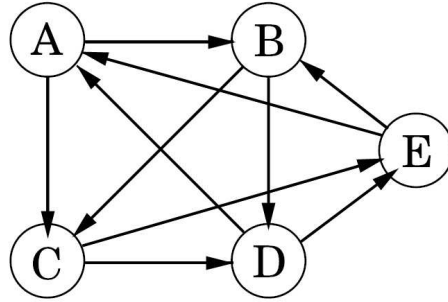
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- Important observation: If there is a path from a to z via s then there must be a path from a to s and from s to z
- Let A^k be the optimal answer when we only allow the first k nodes to be intermediate nodes in paths. We can compute the optimal solution for $k + 1$ nodes A^{k+1} efficiently
- What is A^0 ?
- For $k > 0$,

$$A^{k+1}[i, j] = \begin{cases} 1 & (A^k[i, j] = 1) \\ A^k[i, k] \text{ and } A^k[k, j] & (\text{otherwise}) \end{cases}$$

Warshall's Algorithm

□ Example:



via \emptyset	A	B	C	D	E	via A	A	B	C	D	E
A						A					
B						B					
C						C					
D						D					
E						E					
via B	A	B	C	D	E	via C	A	B	C	D	E
A						A					
B						B					
C						C					
D						D					
E						E					
via D	A	B	C	D	E	via E	A	B	C	D	E
A						A					
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Warshall's Algorithm

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□ Algorithm

Algorithm 0.1: WARSHALL($A[1 \dots n]$)

```
for  $i \leftarrow \{1 \dots n\}$ 
do { for  $j \leftarrow \{1 \dots n\}$ 
do { for  $k \leftarrow \{1 \dots n\}$ 
do  $A^k[i, j] \leftarrow (A^{k-1}[i, k] \text{ and } A^{k-1}[k, j]) \text{ or } A^{k-1}[i, j]$ 
```

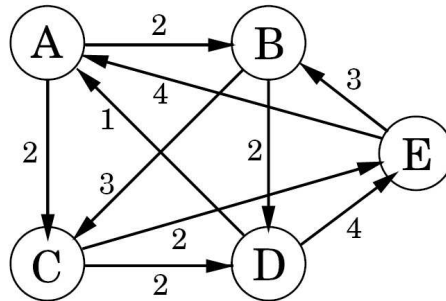
□ Time complexity?

All-pairs Shortest path problem

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- In this problem we want to find the shortest paths connecting all possible pairs of vertices of a graph

- Example:



- What is the brute force algorithm and its time complexity?

Floyd's Algorithm

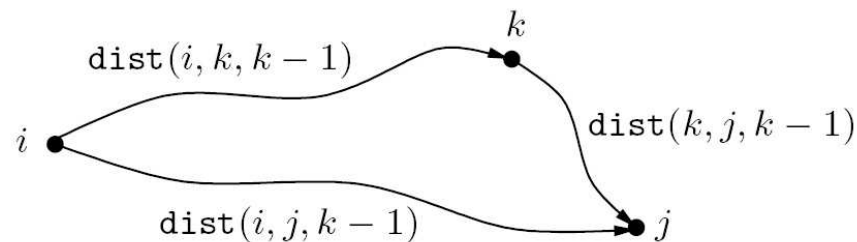
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- A.k.a. Floyd-Warshall algorithm (or the Roy-Floyd algorithm)
- Robert Floyd (1936-2001)



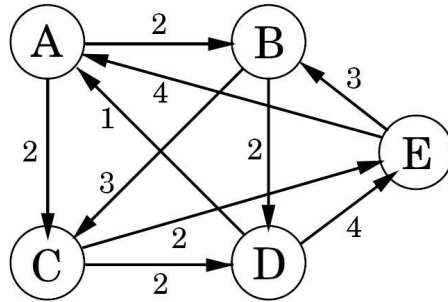
(Robert Floyd, 1972, from <http://sigact.acm.org/floyd/>)

- The algorithm is very similar to Warshall's algorithm
- **Basic idea:** Let A^{k-1} be the optimal answer when we only allow the first $k - 1$ nodes to be intermediate nodes in paths. We can compute the optimal solution for k nodes A^k efficiently



Floyd's Algorithm

□ Example:



via \emptyset	A	B	C	D	E	via A	A	B	C	D	E
A						A					
B						B					
C						C					
D						D					
E						E					
via B	A	B	C	D	E	via C	A	B	C	D	E
A						A					
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□ Algorithm

Algorithm 0.2: FLOYD($A[1 \dots n]$)

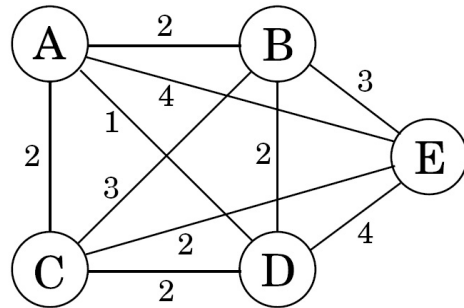
```
for  $i \leftarrow \{1 \dots n\}$ 
do { for  $j \leftarrow \{1 \dots n\}$ 
do { for  $k \leftarrow \{1 \dots n\}$ 
do  $A^k[i, j] \leftarrow \min\{(A^{k-1}[i, k] + A^{k-1}[k, j]), A^{k-1}[i, j]\}$ 
```

□ Time complexity?

Travelling Salesman Problem (TSP)

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- **Problem:** Find the shortest path from A to A by visiting each vertex exactly once



- **Brute force:**
- **Greedy:**
- **Dynamic programming:**

Travelling Salesman Problem (TSP)

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- Given a graph with n nodes and starting vertex is 1.
- Algorithm

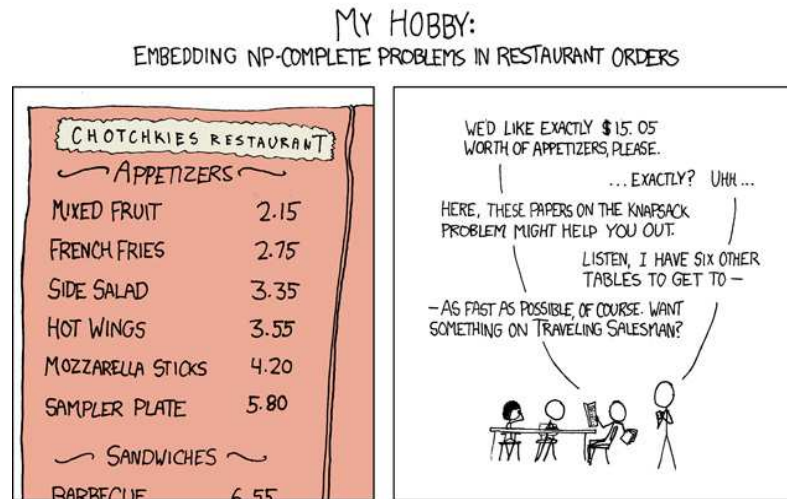
Algorithm 0.3: FLOYD($A[1 \dots n]$)

```
for  $s \leftarrow \{2 \dots n\}$ 
do { for all subsets  $S \subset \{1, 2, \dots, n\}$  of size  $s$  and containing 1
    do { for  $j \in S$  and  $j \neq 1$ 
        do  $C(S, j) = \min_{i \in S, i \neq j} \{C(S - \{j\}, i) + d_{ij}\}$ 
```

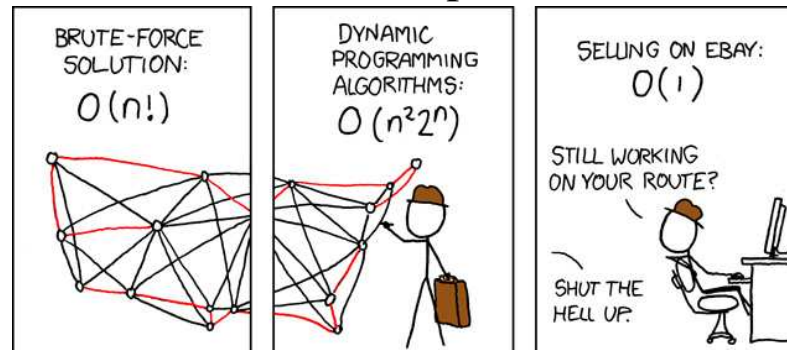
- Time complexity?

Conclusion

- Now you should understand these (better):



NP-Complete



Travelling Salesman Problem
(from Randall Munroe, creator of xkcd)

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▷ Conclusion

- We have solved the following problems using dynamic programming
 - Longest increasing sequence
 - Binomial coefficients of $(a + b)^n$ (Pascal's triangle)
 - Knapsack problem
 - Edit distance
 - Matrix multiplication chain (optimal binary tree)
 - Transitive closure (Warshall's algorithm)
 - All pairs shortest paths (Floyd's algorithm)
 - TSP
- It is usually more difficult to represent a problem as a set of sub-problems
- Next couple of weeks: Linear programming.