

# CS 483 - Data Structures and Algorithm Analysis

## Lecture V: Chapter 5, part 1

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# Outline

- 1 Introduction to Decrease-And-Conquer
- 2 The INSERTIONSORT Algorithm
- 3 Depth-First and Breadth-First Searching
- 4 Homework



# Decrease-And-Conquer

- Decrease-and-conquer exploits the relationship between a solution to a given problem instance and a solution to a smaller instance of the same problem
- Divide-and-conquer attempts to solve separate pieces of the problem, then combine the pieces into an answer, while Decrease-and-conquer attempts to say something about the total solution in terms of the solution to the smaller piece
- Can be approached top-down (recursively) or bottom-up
- Three variations:
  - decrease by a constant — Each iteration, the size of a problem instance is reduced by a constant (e.g.,  $n - 1$ )
  - decrease by a constant factor — Each iteration, the size of a problem instance is reduced by a constant factor (e.g.,  $\frac{n}{2}$ )
  - variable size decrease — The reduction pattern varies with each iteration (e.g., EUCLID)

# Simple Examples of Decrease-and-Conquer

Consider the problem of computing  $f(n) = a^n$ :

- Decrease by a constant:

$$f(n) = \begin{cases} f(n-1) \cdot a & \text{if } n > 1 \\ a & \text{if } n = 1 \end{cases}$$

- Decrease by a constant factor:

$$a^n = \begin{cases} (a^{n/2})^2 & \text{if } n > 0 \text{ is even} \\ (a^{(n-1)/2})^2 \cdot a & \text{if } n > 1 \text{ is odd} \\ a & \text{if } n = 1 \end{cases}$$

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- ★ We are *not* solving *each piece*

- ★ We are using knowledge about how the solution to the piece relates to the whole problem

- ★ Decrease by a constant factor:

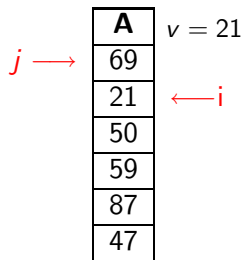
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- ★  $O(\lg n)$

# Specifying INSERTIONSORT

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INSERTIONSORT( $A[0 \dots n - 1]$ )
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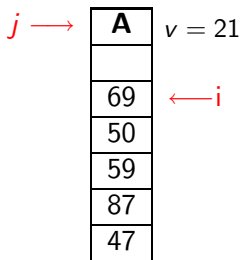
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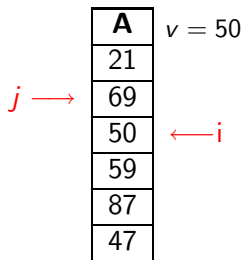
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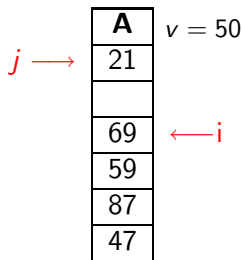




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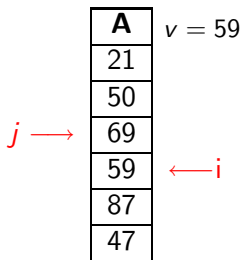
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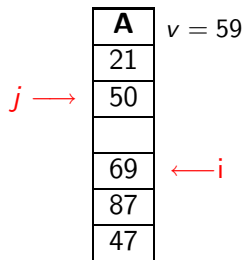
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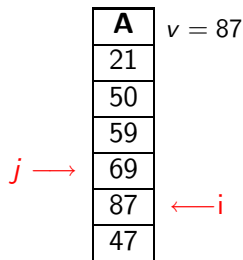
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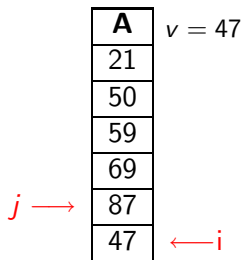
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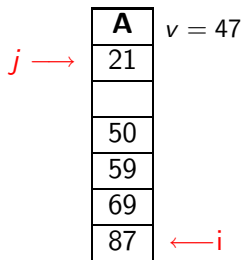
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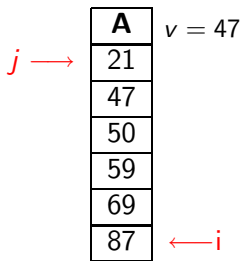
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It's like arranging cards in your hand!

# Comments About INSERTIONSORT

- When dealing with  $A[n - 1]$ , we assume that the  $A[0 \dots n - 2]$  problem has already been solved
- We find an appropriate position for  $A[n - 1]$  and insert it
- The *idea* of this algorithm is recursive, but a bottom-up, iterative implementation is typically best
- One way to speed up insertion is to use `BINARYSEARCH` to find the position (aka *binary insertion sort*)



# Analyzing (Straight) INSERTIONSORT

We count  $A[j] > v$  comparisons, analysis depends on data ...

- Worst case:
  
  
  
  
  
  
  
  
  
  
- Best case:
  
  
  
  
  
  
  
  
  
  
- Average case:

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  - All elements in the sublist are shifted every insertion
  - This occurs when  $A$  is initially strictly decreasing
  - $C_{worst}(n) = \sum_{i=1}^{n-1} \sum_{j=0}^{i-1} i = \frac{(n-1)n}{2} \in \Theta(n^2)$
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## ■ Best case:

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## ■ Average case:

- Investigate number of pairs of elements that are out of order
- On randomly ordered arrays, INSERTIONSORT makes on average half as many comparisons as on decreasing arrays
- $C_{avg}(n) \approx \frac{n^2}{4} \in \Theta(n^2)$

# Searching Graphs

- Solutions to many problems involve searching through a graph
- There are a variety of ways of to search a graph ...
- But there's a simple generalization for many methods:

```
GRAPHSEARCH(G, a)
```

```
WaitingList ←  $\langle a \rangle$ 
```

```
VisitedList ←  $\langle \rangle$ 
```

```
while not EMPTY(WaitingList)
```

```
    v ← GETANDREMOVEITEM(WaitingList)
```

```
    ChildrenList ← GETCHILDVERTICES(G, v)
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```
    ADDLISTTOLIST(WaitingList, ChildrenList)
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    ADDITEMTOLIST(VisitedList, v)
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DFS, BFS, Best-First, and A\* are all instances of this method, depending on the list structure. DFS uses a Stack; BFS uses a queue

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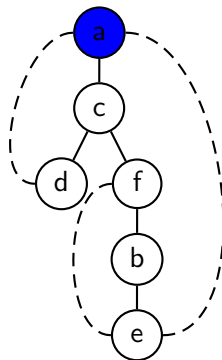
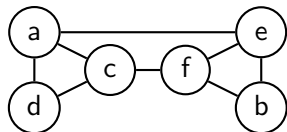
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**WARNING:** The algorithms in the book are presented differently, but they are the same in spirit.

# Depth-First Searching: An Example



Stack =  $\langle a \rangle$

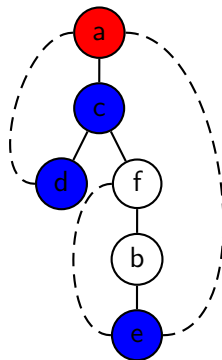
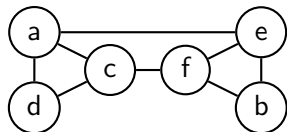
Visited =  $\langle \rangle$

Dead =  $\langle \rangle$

- For adjacency matrix representation, traversal time is  $\Theta(|V|^2)$
- For adjacency list representation, traversal time is  $\Theta(|V| + |E|)$
- We can use the algorithm to check for connectivity & cycles, and to find articulation points



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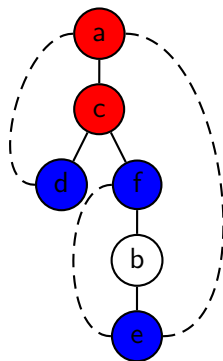
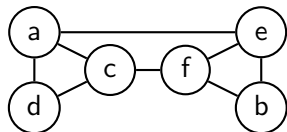
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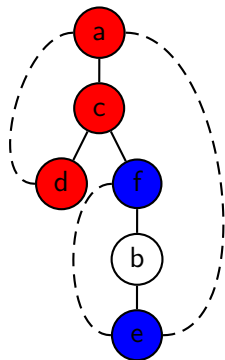
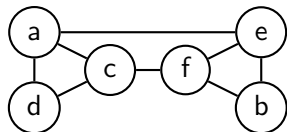
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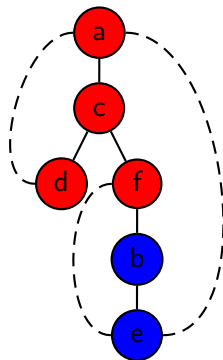
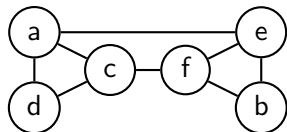
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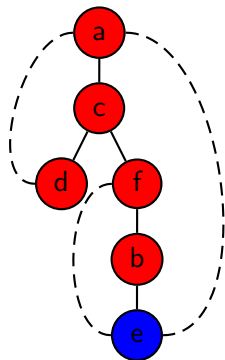
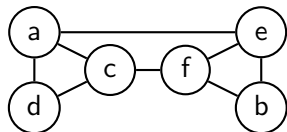
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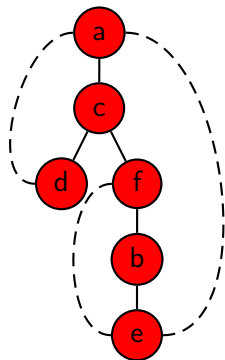
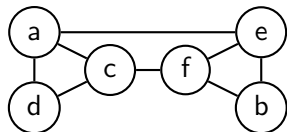
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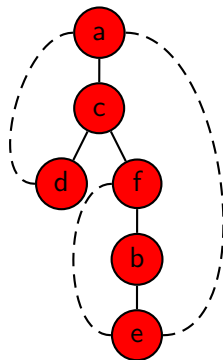
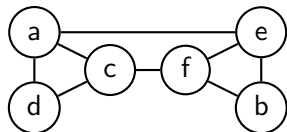
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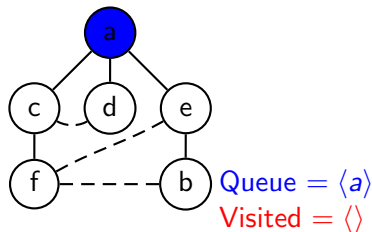
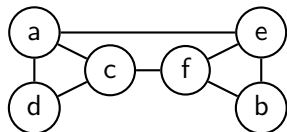
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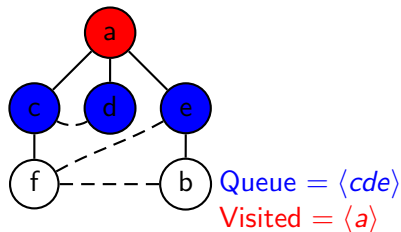
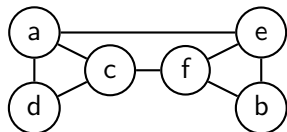
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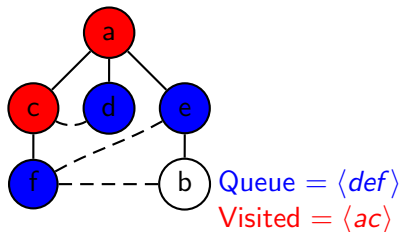
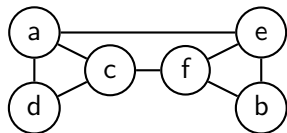


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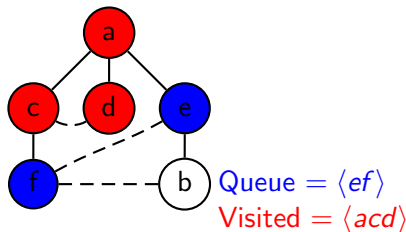
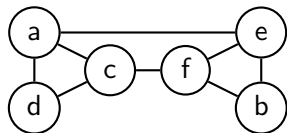
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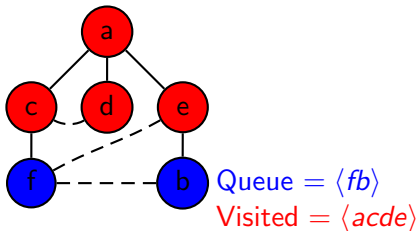
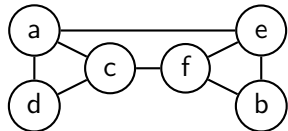
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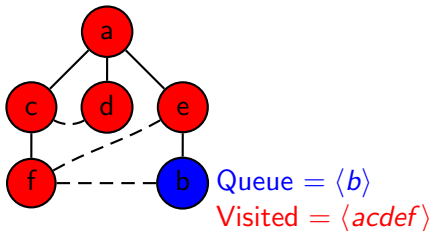
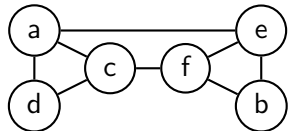
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# Breadth-First Searching: An Example



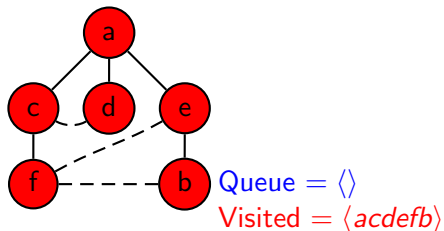
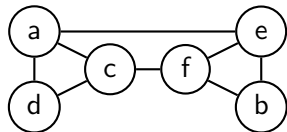
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- For adjacency list representation, traversal time is  $\Theta(|V| + |E|)$
- We can use the algorithm to check for connectivity & cycles, and to find minimum paths

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# Assignments

- This week's assignments:
  - Section 5.1: Problems 4, 6, and 9
  - Section 5.2: Problems 1, 4, and 7