RESEARCH STATEMENT

I envision future after-disaster missions to be efficiently conducted by fully autonomous robots, which are (1) highly capable of reliably moving through challenging and most likely adversarial environments, and (2) highly intelligent so that involvement of human rescuers, both physically and intellectually, can be effectively minimized. Therefore, my research goal is to develop highly capable and intelligent mobile robots that are robustly deployable in the real world with minimal human supervision. As a roboticist with unique expertise evenly grounded in motion planning and machine learning, and vast experience working on real-world problems in the field with disaster responders, I build advanced robot platforms, develop complex sensing and actuation systems, design sophisticated motion planning algorithms, and set up standardized testbeds and metrics in order to create highly capable and intelligent robots to locomote on land, in air, and at sea.

PROFESSIONAL PREPARATION

• Ph.D. (Computer Science, 2019), Texas A&M University, College Station, TX
  Dissertation: Risk-aware Path and Motion Planning for a Tethered Aerial Visual Assistant in Unstructured or Confined Environments
  Thesis Committee: Robin R. Murphy (Chair), Dylan A. Shell, Thomas R. Loerger, Suman Chakravorty
• Master of Science (Mechanical Engineering, 2015), Carnegie Mellon University, Pittsburgh, PA
  Advisor: William (Red) L. Whittaker
• Bachelor of Engineering (Mechatronics Engineering, Dual-Degree, 2013), Tongji University, Shanghai, P.R. China
  FH Aachen University of Applied Sciences, Aachen, North Rhine-Westphalia, Germany

APPOINTMENTS

Academia

• George Mason University, 08/2022-current
  Assistant Professor, Department of Computer Science
• University of Texas at Austin, 06/2021-08/2022
  Research Affiliate, Learning Agents Research Group (LARG)
• University of Texas at Austin, 08/2019-05/2021
  Postdoctoral Researcher, Learning Agents Research Group (LARG)
• Texas A&M University, 08/2015-08/2019
  Graduate Research Assistant, Center for Robot-Assisted Search and Rescue (CRASAR)
• Carnegie Mellon University, 08/2014-05/2015
  Graduate Research Assistant, Biorobotics Lab
Carnegie Mellon University, 09/2013-11/2014  
*Graduate Research Assistant*, Field Robotics Center

Industry

- **Everyday Robots, X, The Moonshot Factory**, 06/2021-current  
  *Roboticist*, Mountain View, CA
- **Facebook Reality Labs**, 05/2018-08/2018  
  *Research Intern*, Sausalito, CA
- **Microsoft Research Labs**, 05/2017-08/2017  
  *Research Intern*, Redmond, WA
- **PHOENIX CONTACT GmbH & Co. KG**, 02/2013-06/2013  
  *Intern & Bachelor Thesis Author*, Blomberg, Germany
- **DELPHI China Technical Center**, 06/2012-08/2012  
  *Advanced Intern*, Shanghai, China
- **Siemens Industrial Automation Ltd., Shanghai**, 05/2011-09/2011  
  *Assistant Engineer*, Shanghai, China
- **Luther Attorneys Shanghai**, 07/2010-08/2010  
  *Executive Assistant*, Shanghai, China

**PUBLICATIONS**

**Journal**


Xuesu Xiao, Page 2 of 11


Conference


Workshop / Extended Abstract


Preprint

Z. Xu, B. Liu, X. Xiao, A. Nair, and P. Stone. Benchmarking Reinforcement Learning Techniques for...


Technical Report


Dissertation


Patent


SELECTED FUNDING

- Clearpath Robotics OutdoorNav Developer Partner Program, 12/2022
  Selected Partner (~$30K), up to 90% discount in software licenses and 30% to 60% in hardware and sensor kits to build innovative off-road autonomous systems
- Robotics@Google In-Kind Donation Award, 11/2022
  Grantee (~$300K), robot platforms donated by Robotics@Google including two Fetch robots and one Clearpath Husky for collaborative navigation and manipulation research
- Learning Kinodynamics for Accurate, High-Speed, Off-Road Ground Maneuvers on Unstructured Terrain, 12/2022-current
  PI ($817K), Award Number: W911NF-23-2-0004, AI/ML Research for Expeditionary Maneuver and Air/Ground Reconnaissance funded by US Army Research Laboratory
- Tactical Team Behavior with Hierarchical Decision Making using Game Theory and Learning, 09/2022-current
  Co-PI ($481K), Award Number: W911NF-22-2-0242, Tactical Behaviors for Autonomous Maneuver Collaborative Research Program (TBAM-CRP)-Cycle 1 Sprint Topic: Coordinated and adversarial tactical maneuver in complex terrains funded by US Army Research Laboratory
- Inspection of City Infrastructure via Peripheral Perception, 09/2020-08/2021
  Project Lead ($150K), Good Systems Grand Challenge funded project at University of Texas at Austin
  Project Lead ($200K), Army Research Laboratory (ARL) Collaborative Research Alliance (CRA) funded Distributed and Collaborative Intelligent Systems and Technology (DCIST) project at University of Texas at Austin
- NRI: A Collaborative Visual Assistant for Robot Operations in Unstructured or Confined Environments, 09/2016-08/2019
  Project Lead ($609K), Department of Energy funded NSF NRI project at Texas A&M University
- NRI: Collaborative: Exploiting Granular Mechanics to Enable Robotic Locomotion, 05/2016-08/2019
  Main Participant, NSF NRI funded project at Texas A&M University
- NSF RAPID: Using an Unmanned Aerial Vehicle and Increased Autonomy to Improve an Unmanned Marine Vehicle Lifeguard Assistant Robot, 01/2016-08/2019
  Project Lead, NSF funded project at Texas A&M University
  Main Participant, NSF NRI funded project at Carnegie Mellon University

INVITED TALKS

“Learning Agile Ground Maneuvers in Highly Constrained and Off-Road Conditions”
- Invited Talk @ Learning for Agile Robotics Workshop, 2022 Conference on Robot Learning (CoRL), Auckland, New Zealand 12/15/2022

“Motion Planning for Deployable Robots”
- Guest Lecture for CS 700 @ George Mason University, Fairfax, VA 11/07/2022
“Evaluating Motion Planning “in-the-Loops” ”

- Invited Talk @ Evaluating Motion Planning Performance Workshop, 2022 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Kyoto, Japan 10/23/2022

“Deployable Robots that Learn”

- Controls and Robotics Reading Group @ George Mason University, Fairfax, VA 10/04/2022
- Seminar Series @ Harbin Institute of Technology, Harbin, China 09/02/2022
- Kavraki Lab @ Rice University, Houston, TX 06/08/2022
- Maryland Robotics Center @ University of Maryland, College Park, MD 04/29/2022
- IFML Talk Series @ The University of Texas at Austin, Austin, TX 04/08/2022
- Robot Mobility @ Google, Mountain View, CA 03/23/2022
- LCSR Seminar @ Johns Hopkins University, Baltimore, MD 02/02/2022
- DEVCOM ARL Colloquium @ Army Research Laboratory, Adelphi, MD 11/17/2021
- Oxford Robotics Institute @ Oxford University, Oxford, UK 11/12/2021
- Department Seminar @ University of Nebraska-Lincoln, Lincoln, NE 03/17/2021
- Department Seminar @ Illinois Institute of Technology, Chicago, IL 03/08/2021
- Department Seminar @ George Mason University, Fairfax, VA 02/24/2021
- LARRI Seminar @ University of Louisville, Louisville, KY 02/12/2021

“High-Speed Motion Control with Learned Kinodynamic Models for Off-Road Navigation”

- Guess Lecture for CS 378H @ The University of Texas at Austin, Austin, TX 03/21/2022

TEACHING

- **CS685 Autonomous Robotics**  
  *Instructor*, George Mason University, Spring 2023

- **CS580 Introduction to Artificial Intelligence**  
  *Instructor*, George Mason University, Fall 2022

- **CS309 Autonomous Intelligent Robotics (FRI II)**  
  *Co-Instructor*, University of Texas at Austin, Fall 2020

- **CS309 Autonomous Intelligent Robotics (FRI I)**  
  *Co-Instructor*, University of Texas at Austin, Spring 2020

- **CSCE 121 Introduction to Program Design and Concepts**  
  *Teaching Assistant*, Texas A&M University, Spring 2016

- **CSCE 121 Introduction to Program Design and Concepts**  
  *Teaching Assistant*, Texas A&M University, Fall 2015

- **Robotics 778 Mechatronic Design**  
  *Teaching Assistant*, Carnegie Mellon University, Spring 2015

STUDENT MENTORSHIP

Ph.D. Thesis Committees

<table>
<thead>
<tr>
<th>Mentor</th>
<th>University</th>
<th>Thesis Defense Date</th>
<th>Thesis Proposal Date</th>
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<tbody>
<tr>
<td>Linh Kästner</td>
<td>Technical University of Berlin</td>
<td>Spring 2023</td>
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<td>Zhanteng Xie</td>
<td>Temple University</td>
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<td>Spring 2023</td>
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<td>Jinsoo Park</td>
<td>The University of Texas at Austin</td>
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George Mason University
Mohammad Nazeri, Ph.D. student 12/2022-current
Dibyendu Das, Ph.D. student 11/2022-current
Manshi Limbu, Ph.D. student 10/2022-current
Anuj Pokhrel, Ph.D. student 09/2022-current
Amir Hossain Raj, Ph.D. student 08/2022-current
Chenhui Pan, Ph.D. student 08/2022-current
Duc (Aaron) M. Nguyen, Ph.D. student 08/2022-current
Aniket Anand Datar, Master student 10/2022-current
Dileep Kumar, Master student 08/2022-current

The University of Texas at Austin
Haresh Karnan, Ph.D. student 12/2020-current
Jinsoo Park, Ph.D. student 08/2020-current
Zizhao Wang, Ph.D. student 08/2020-current
Zifan Xu, Ph.D. student 05/2020-current
Bo Liu, Ph.D. student 12/2019-08/2022
Fulin Jiang, Undergraduate student 05/2022-08/2022
Kevin Hou, Undergraduate student 01/2022-08/2022
James Xu, Undergraduate student 01/2022-08/2022
Ruolin Dong, Undergraduate student 01/2022-08/2022
Anirudh Nair, Undergraduate student 05/2020-08/2022
Daniel Perille, Undergraduate student 05/2020-09/2021
Ashwin Kudva, Undergraduate student 01/2021-06/2021
Gauraang Dhamankar, Undergraduate student 05/2020-05/2021
Abigail Truong, Undergraduate student 05/2020-03/2021
William Shi, Undergraduate student 08/2020-12/2020
Yuntong Qu, Undergraduate student 08/2020-12/2020

Texas A&M University
Jan Dufek, Ph.D. student 08/2019-08/2020
Mohamed Suhail, Master student 08/2017-05/2018
Rebecca Schofield, Undergraduate student 08/2017-05/2018

SERVICE

Chair
- International Joint Conference on Artificial Intelligence (IJCAI) 2023 Robot Exhibition
- IEEE ICRA 2022 Competition The Benchmark Autonomous Robot Navigation (BARN) Challenge
- IEEE ICRA 2021 Workshop Machine Learning for Motion Planning

Organizing Committee
- CoRL 2022 Workshop Learning for Agile Robotics
• ACM/IEEE HRI 2022 Workshop Human-Interactive Robot Learning (HIRL)
• ACM/IEEE HRI 2021 Workshop Exploring Applications for Autonomous Non-Verbal Human-Robot Interactions

Associate Editor
• IEEE International Conference on Robotics and Automation (ICRA)
• IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)
• IEEE International Symposium on Safety, Security, and Rescue Robotics (SSRR)

Senior Program Committee
• International Joint Conferences on Artificial Intelligence (IJCAI)

Program Committee
• AAAI-2023 Student Abstract and Poster Program
• NeurIPS 2022 Workshop on Reinforcement Learning for Real Life
• The AAAI Conference on Artificial Intelligence (AAAI)
• International Conference on Autonomous Agents and Multiagent Systems (AAMAS)
• IEEE ICRA 2020 Workshop Machine Learning in Planning and Control of Robot Motion

Reviewer Board
• MDPI Applied Sciences
• MDPI Sensors

Grant Reviewer
• National Science Foundation

Journal Reviewer
• IEEE Robotics and Automation Letters (RA-L)
• IEEE Robotics and Automation Magazine (RAM)
• IEEE Transactions on Automation Science and Engineering (T-ASE)
• IEEE Transactions on Mobile Computing (TMC)
• IEEE Access
• IEEE Transactions on Cybernetics (TCYB)
• IEEE Transactions on Cognitive and Developmental Systems (TCDS)
• ACM Transactions on Human-Robot Interaction (THRI)
• Elsevier Robotics and Autonomous Systems (RAS)
• Wiley Journal of Field Robotics
• AI Access Foundation Journal of Artificial Intelligence Research (JAIR)
• MDPI Journal of Marine Science and Engineering (JMSE)
• Springer Machine Learning
• SAGE Measurement and Control (MAC)
• SCIENCE CHINA Information Sciences

Conference Reviewer
• Robotics: Science and Systems (RSS)
• IEEE International Conference on Robotics and Automation (ICRA)
• IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)
• IEEE International Symposium on Safety, Security, and Rescue Robotics (SSRR)
• ACM/IEEE International Conference on Human-Robot Interaction (HRI)
• IEEE International Symposium on Multi-Robot and Multi-Agent Systems (MRS)
• IEEE European Conference on Mobile Robots (ECMR)
• International Conference on Machine Learning (ICML)
International Conference on Learning Representations (ICLR)
Conference on Neural Information Processing Systems (NeurIPS)

Departmental and University Committee
Tenure-Track Recruitment Committee 2022-2023, Department of Computer Science, George Mason University

PRESS COVERAGE

- Clearpath Robotics, **Jackal UGV Shines in ICRA 2022 Autonomous Navigation Challenge**, 06/07/2022
- IEEE Spectrum, **How the US Army is Turning Robots into Team Players**, 09/23/2021
- US Army, **Soldiers could teach future robots how to outperform humans**, 08/12/2020
- Robotics Business Review, **How Robots and Drones are Changing Rescue Operations**, 11/27/2019
- Tech Briefs, **Drones and AI Improve ‘EMILY’ Lifesaver Robot for Large-Scale Water Rescues**, 06/30/2018
- NSF Science Nation, **Water rescue robot EMILY gets some help from the sky**, 02/26/2018
- WIRED, **Marsupial Robots Ain't Cuddly, But They Are Totally Brilliant**, 04/08/2017
- KBTX, **Search and rescue workers, drones, robots, gather in Grimes County for training**, 01/28/2017

HONORS

- George Mason University Teaching Excellence Award Nomination (11/2022)
- 2018 IEEE International Conference on Wearable and Implantable Body Sensor Networks (BSN), Student Travel Award (03/2018)
- The Excellent Graduate of Shanghai (06/2013)
- DAAD Scholarship (German Ministry of Education) (09/2012)
- National Scholarship (Chinese Ministry of Education) (09/2012)
- Learning Scholarship of Tongji University (09/2012)
- The Excellent Student of Tongji University (09/2012)
- National Scholarship (Chinese Ministry of Education) (09/2011)
- Learning Scholarship of Tongji University of the School Year 2010-2011 (09/2011)
- The Excellent Student of the School Year 2010-2011 of Tongji University (09/2011)
- Ni-Li-Shi Scholarship (awarded to the best students) (09/2010)
- Learning Scholarship of Tongji University of the School Year 2009-2010 (09/2010)
- The Excellent Student of the School Year 2009-2010 of Tongji University (09/2010)

PERSONAL

Languages:
- Chinese (native)
- English (fluent)
- German (fluent)