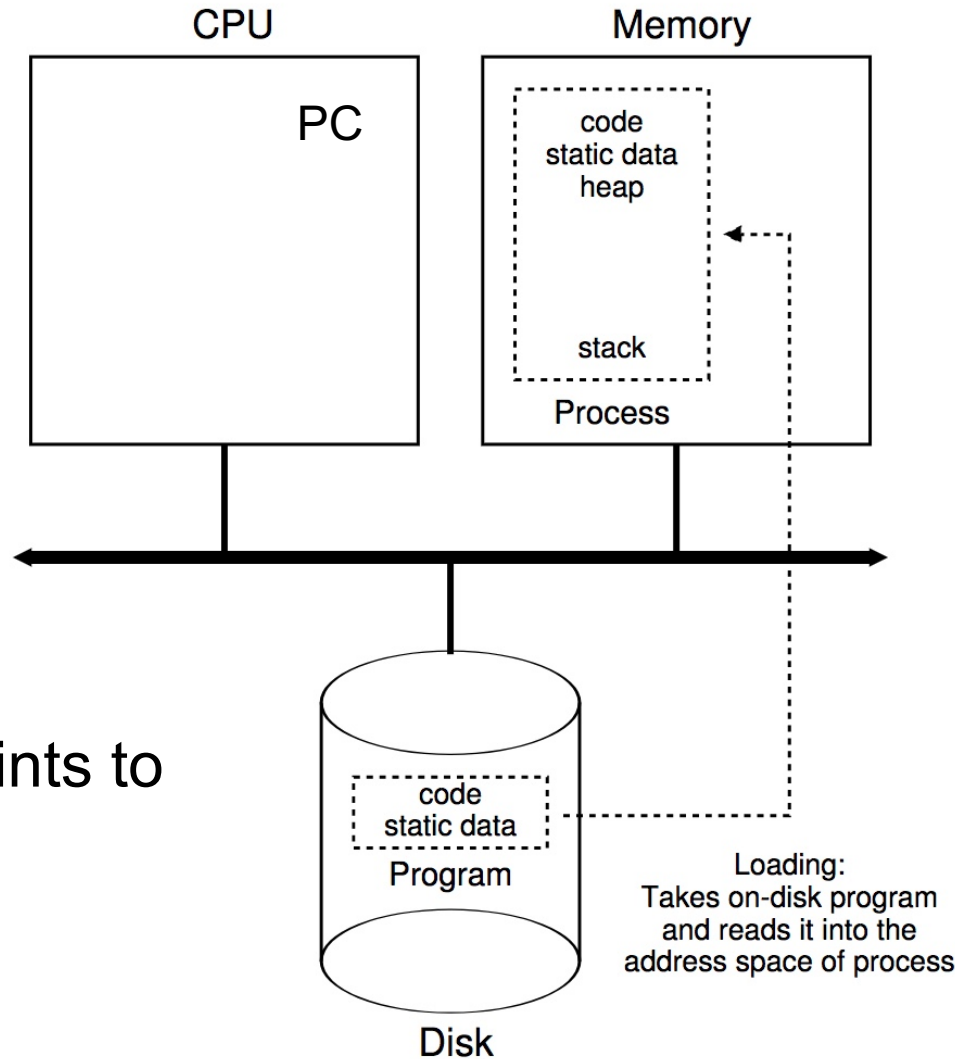


# CS 471 Operating Systems

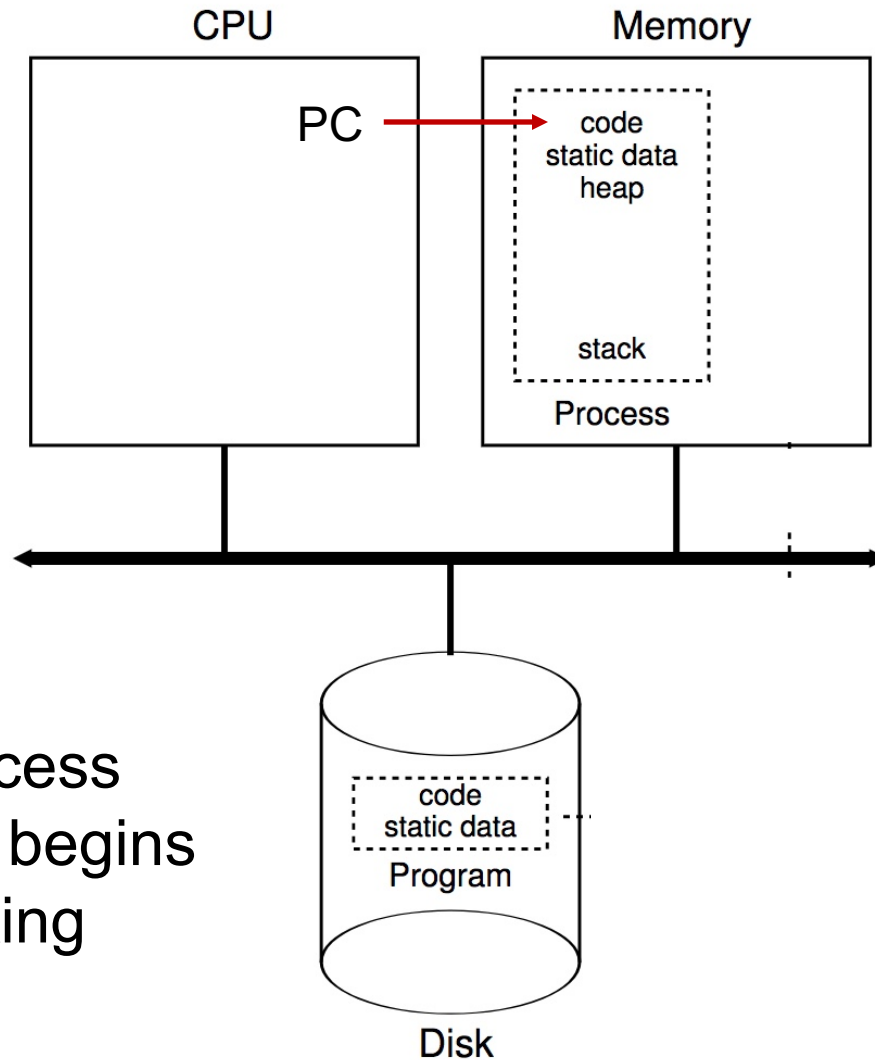
Yue Cheng

George Mason University  
Fall 2019

# Process Creation

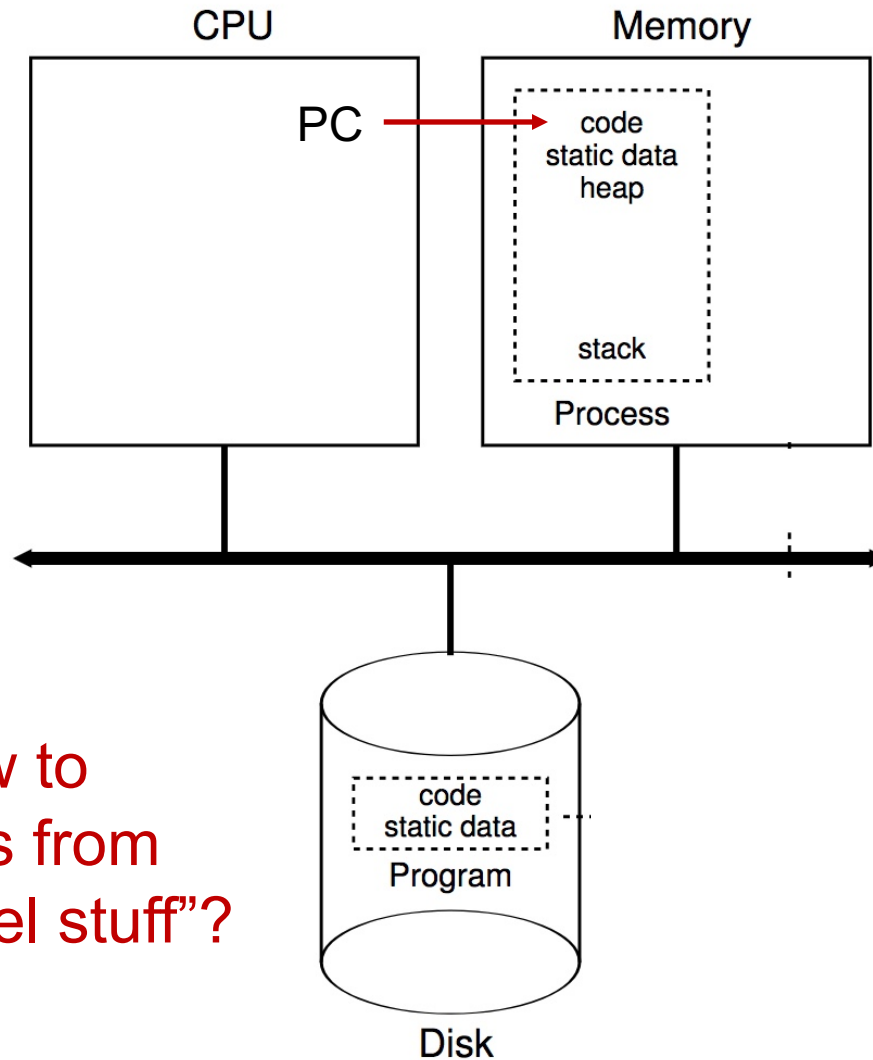


# Process Creation



Now, after process creation, CPU begins directly executing process code

# Process Creation



**Challenge:** how to prevent process from doing “OS kernel stuff”?

# Limited Direct Execution (LDE)

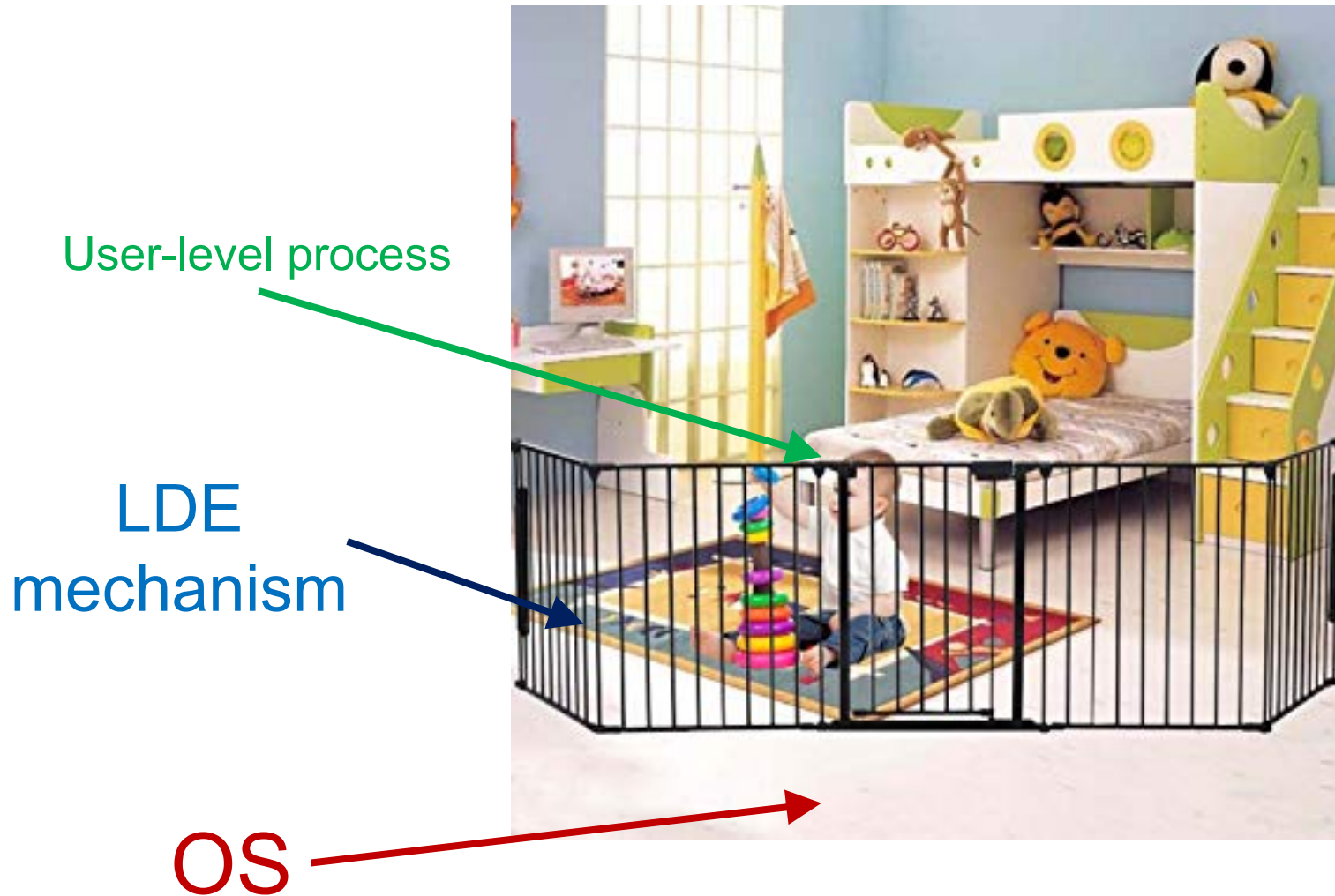
# Limited Direct Execution (LDE)

- Low-level mechanism that implements the user-kernel space separation
- Usually let processes run with no OS involvement
- Limit what processes can do
- Offer privileged operations through well-defined channels with help of OS

# Limited Direct Execution (LDE)



# Limited Direct Execution (LDE)





# What to limit?

- General memory access
- Disk I/O
- Certain x86 instructions

# How to limit?

- Need hardware support
- Add additional execution mode to CPU
- **User mode**: restricted, limited capabilities
- **Kernel mode**: privileged, not restricted
- **Processes** start in **user mode**
- **OS** starts in **kernel mode**

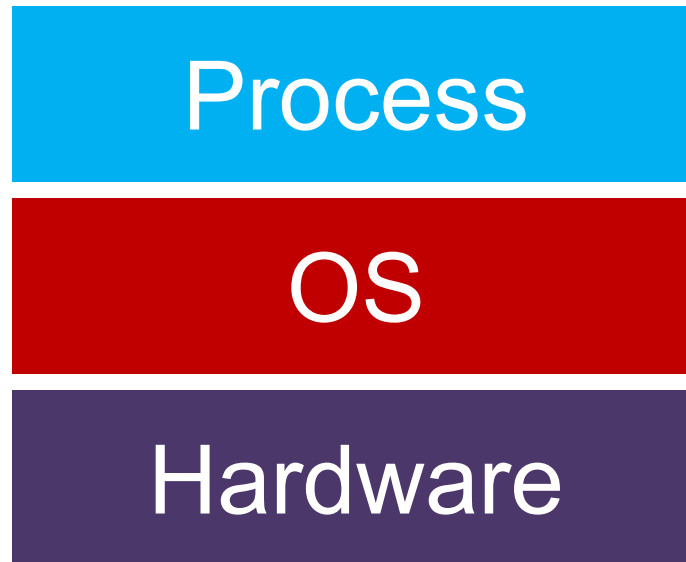
# LDE: Remaining Challenges

1. What if process wants to do something privileged?
2. How can OS switch processes (or do anything) if it's not running?

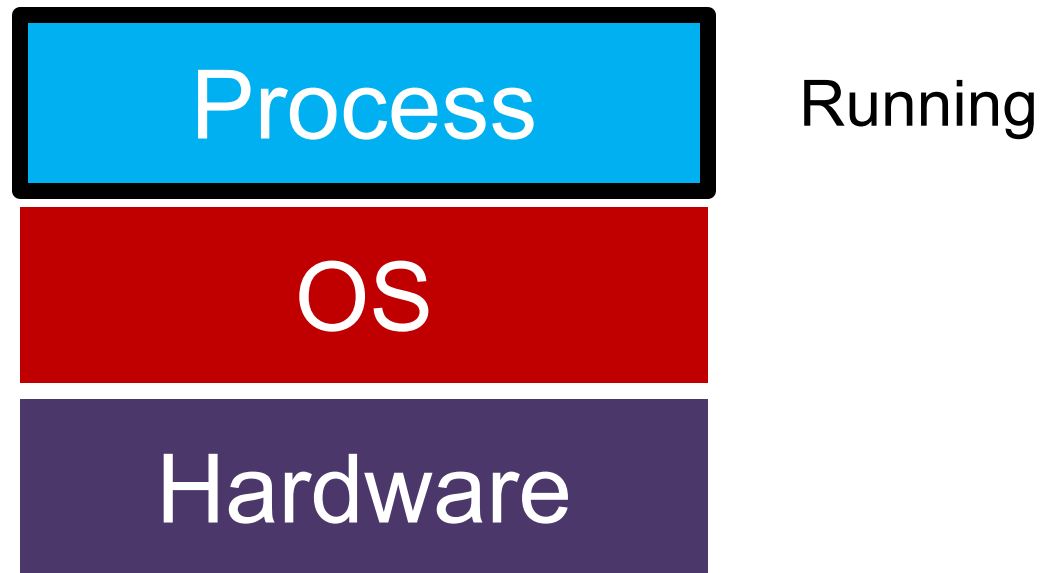
# LDE: Remaining Challenges

- 1. What if process wants to do something privileged?**
2. How can OS switch processes (or do anything) if it's not running?

# Taking Turns

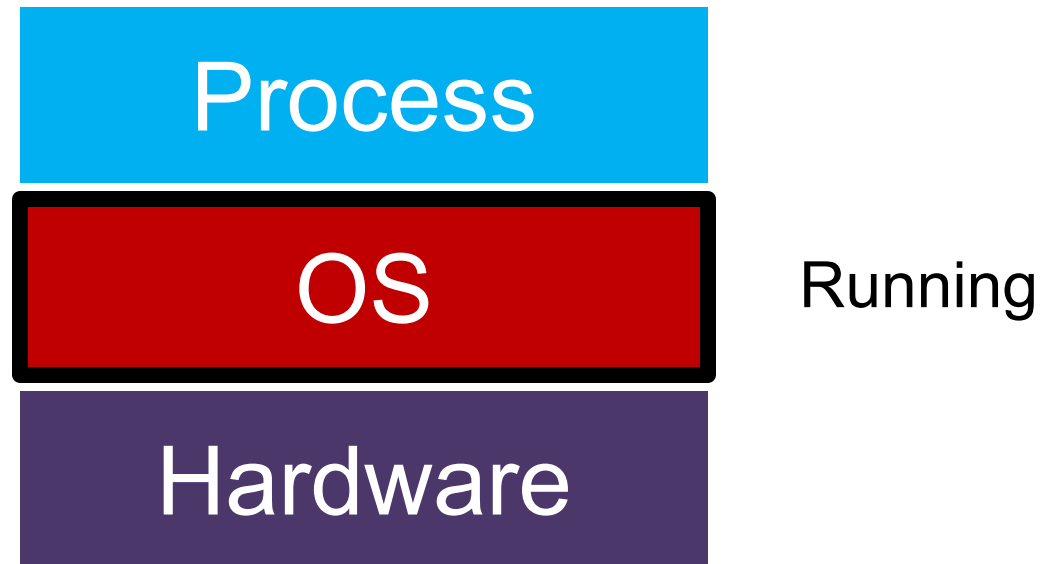


# Taking Turns

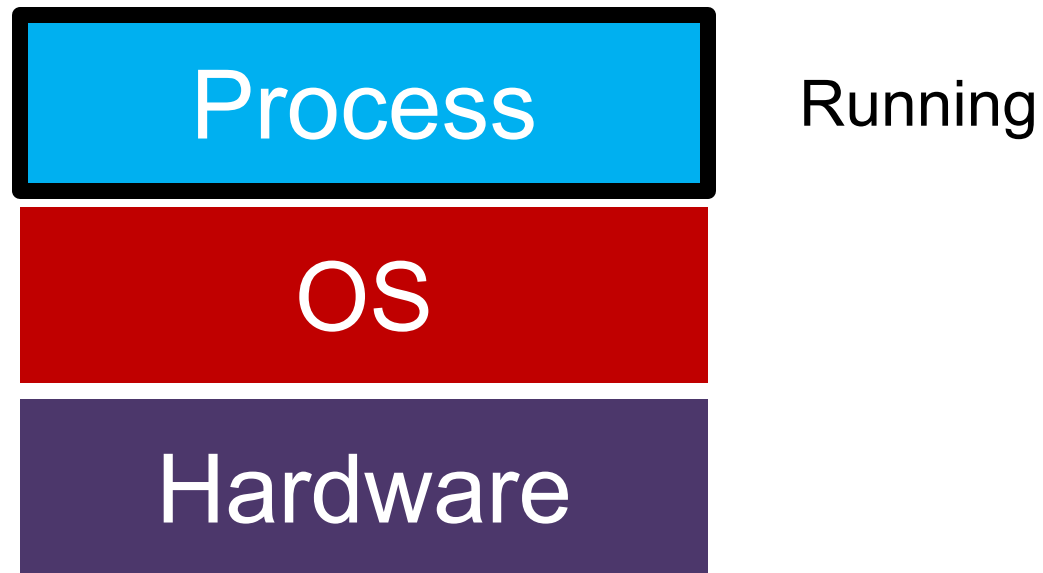


Time:  $\xrightarrow{\text{T1}}$

# Taking Turns

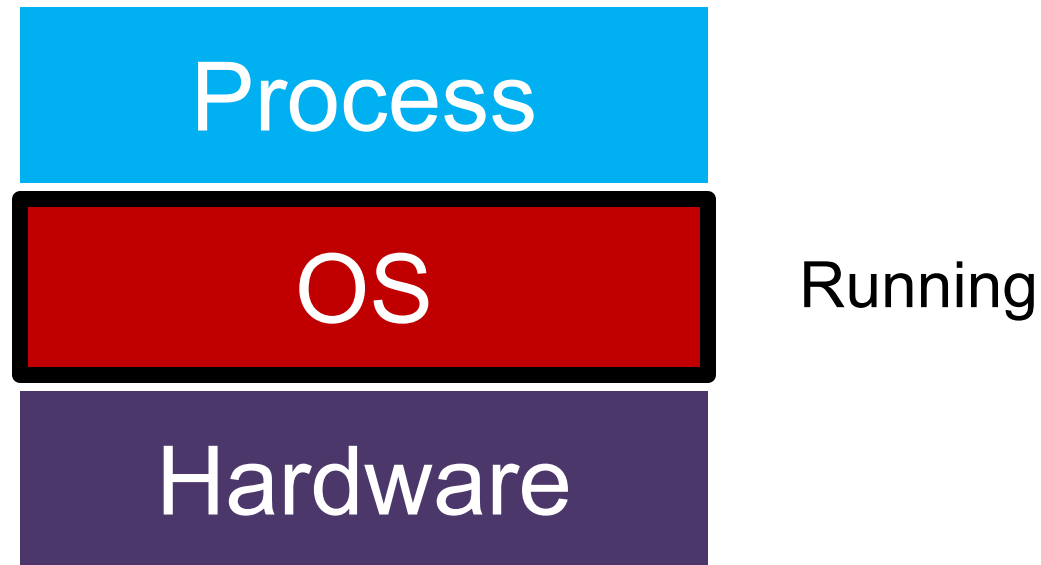


# Taking Turns



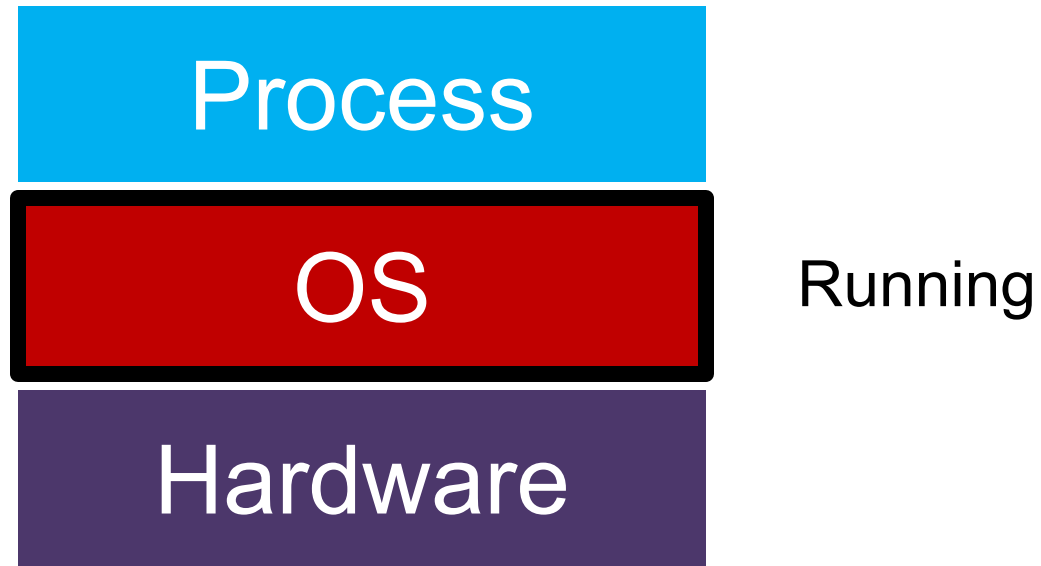


# Taking Turns



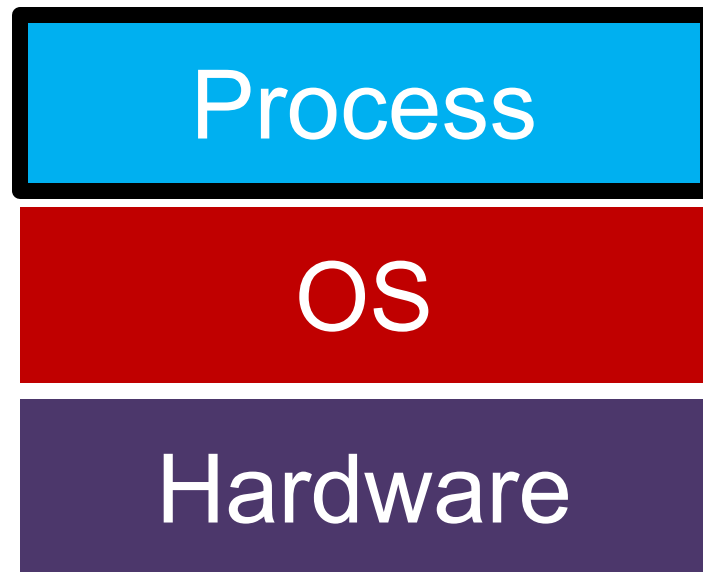
# Taking Turns

**Question:** when/how do we switch to OS?

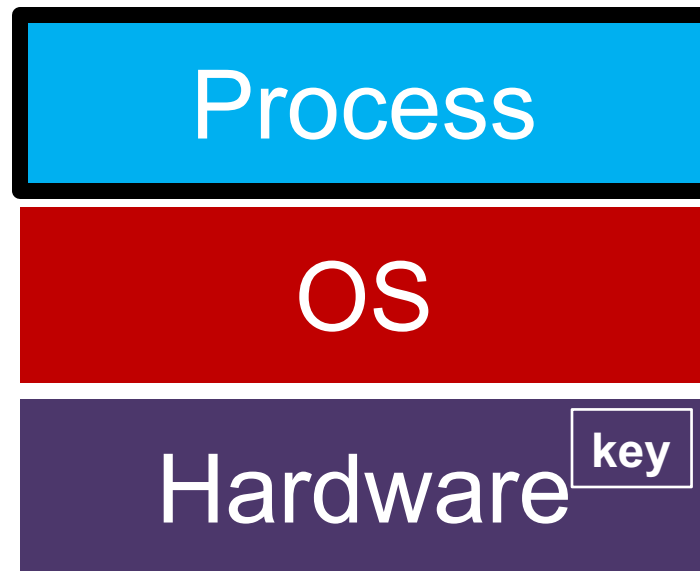


# Exceptions

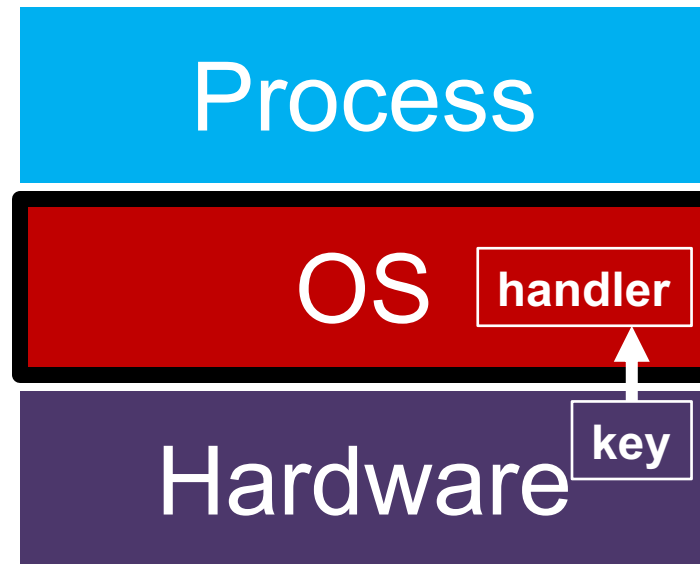
# Interrupt



# Interrupt

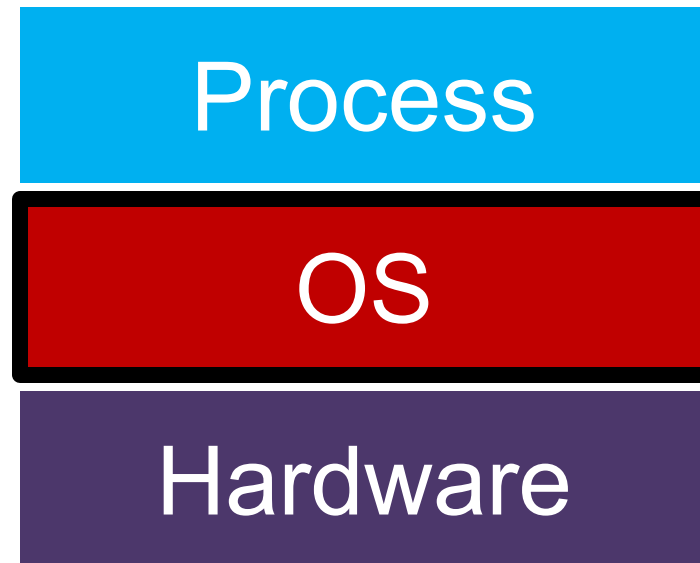


# Interrupt

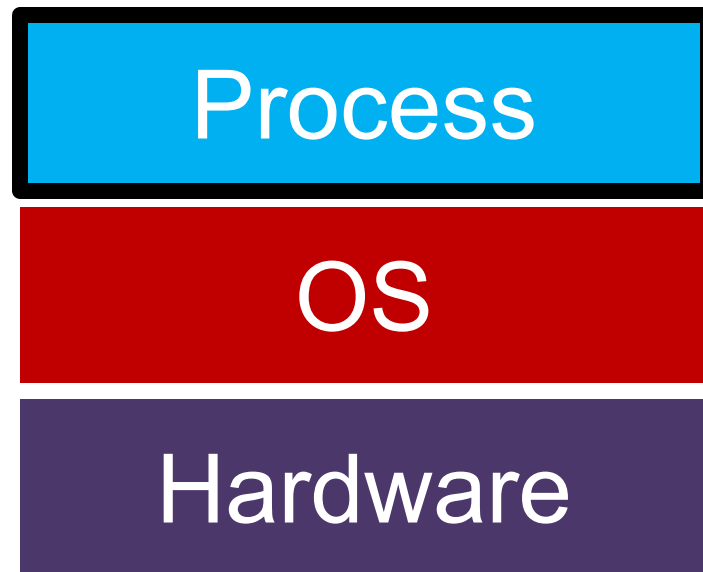


Hardware interrupt

# Interrupt

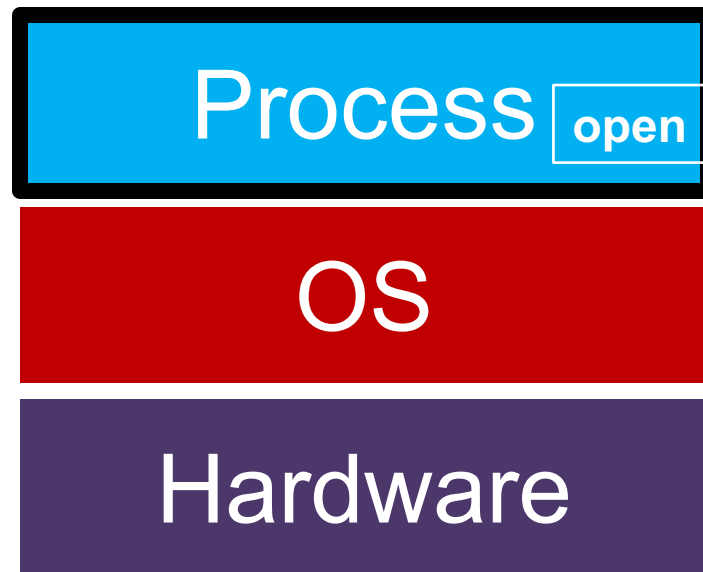


# System Call

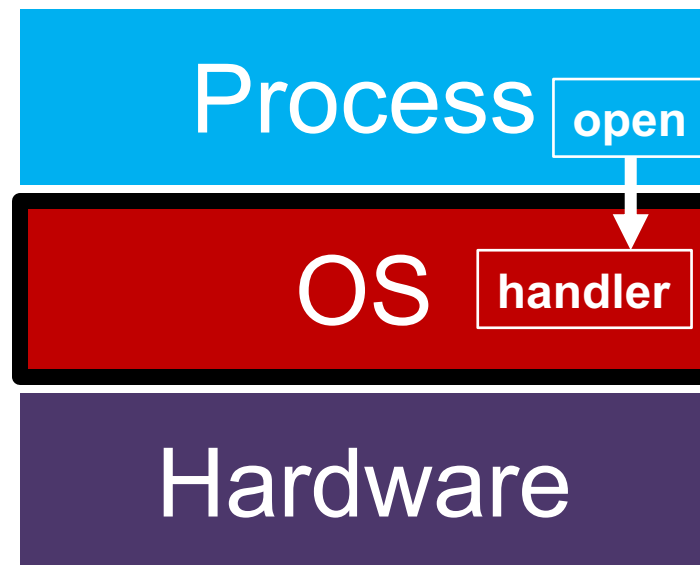




# System Call

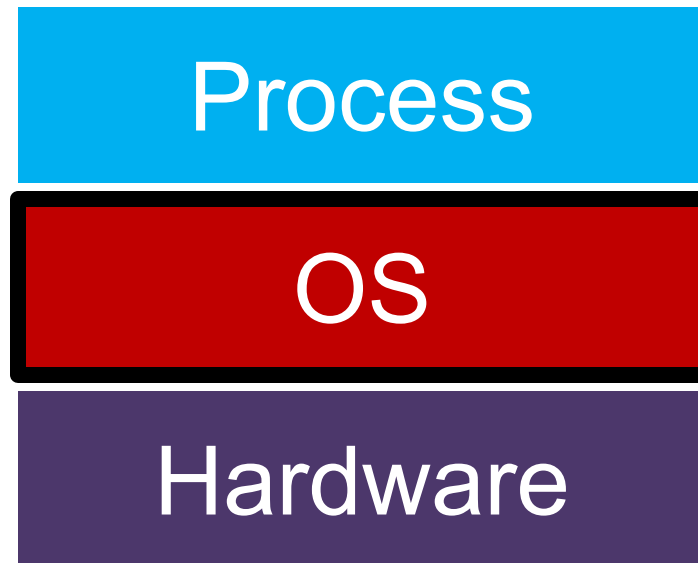


# System Call



System call “trap”

# System Call

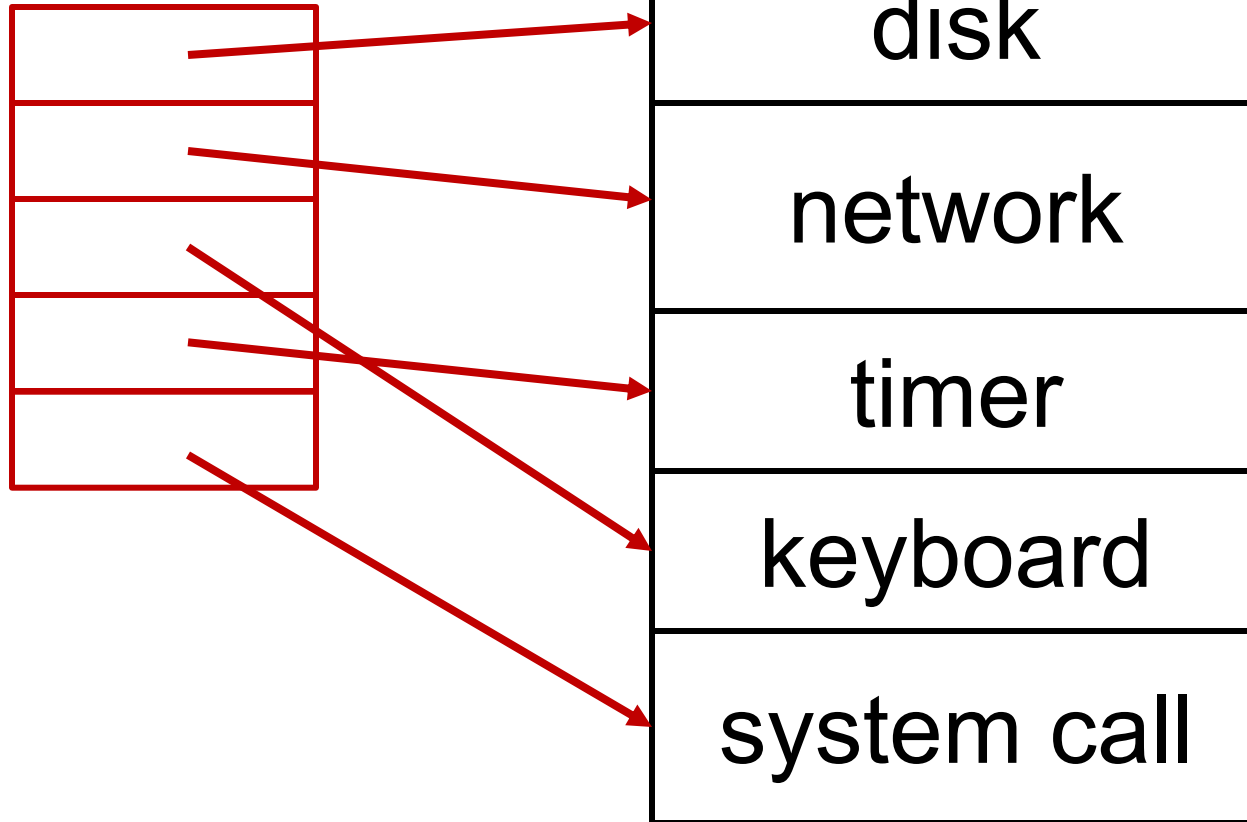


# Exception Handling

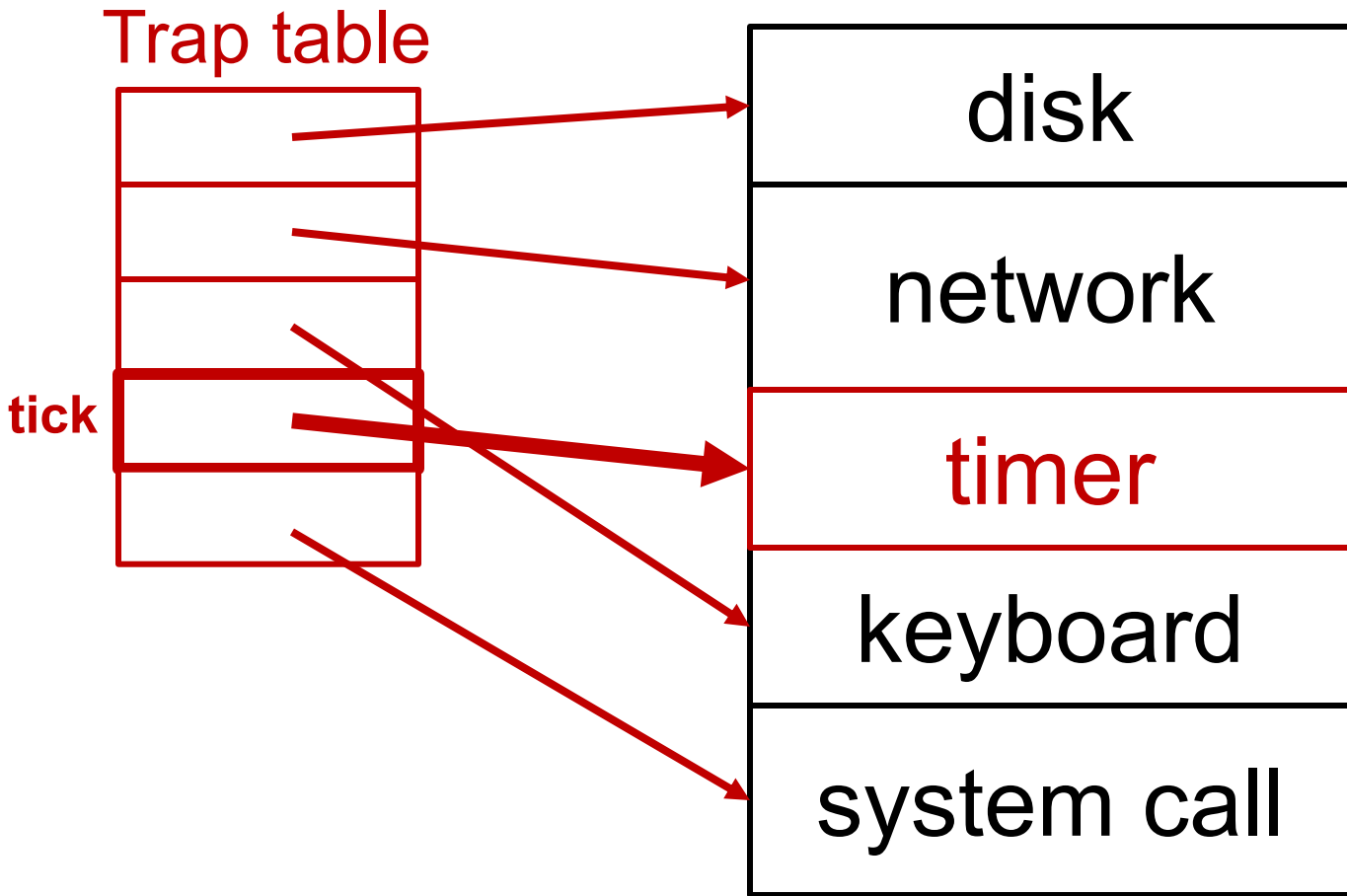
# Exception Handling: Implementation

- Goal: Processes and hardware should be able to call functions in the OS
- Corresponding OS functions should be:
  - At **well-known** locations
  - **Safe** from processes

Trap table

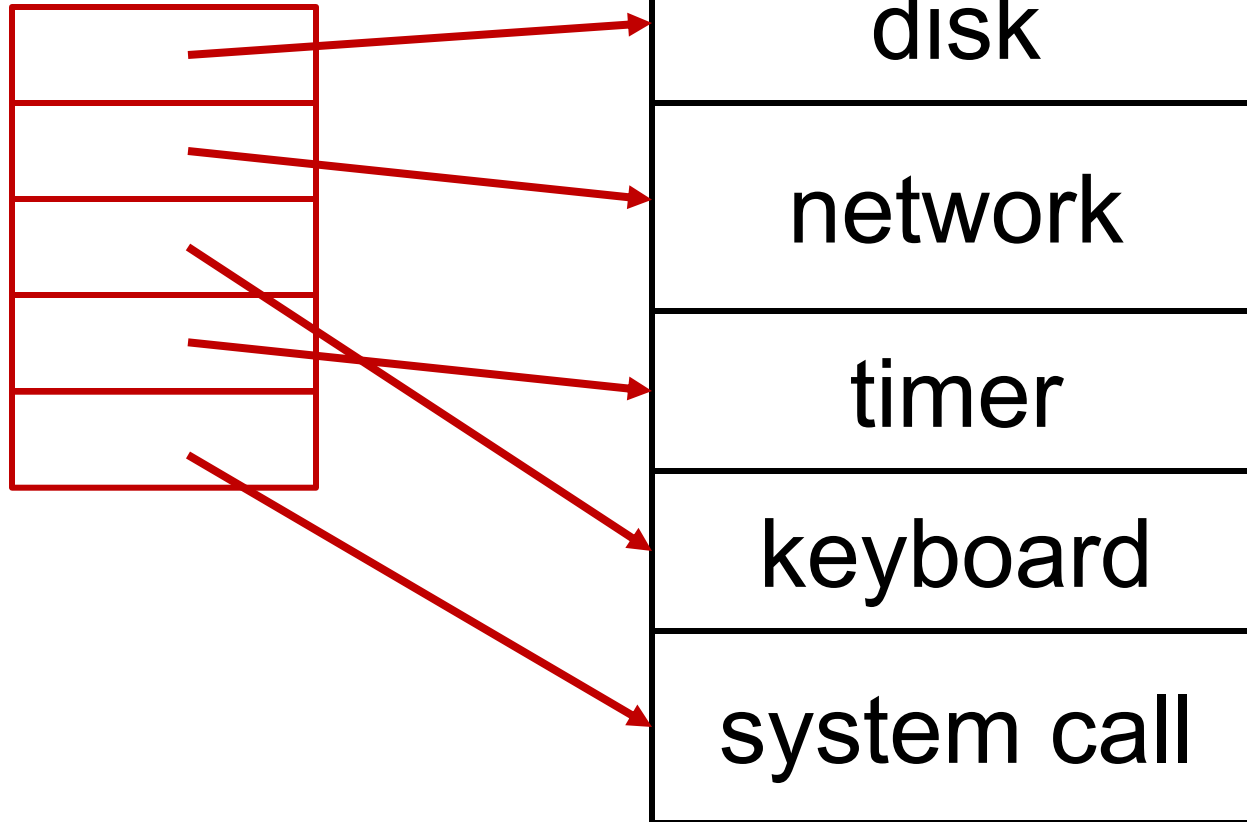


Use array of function pointers to locate OS functions  
**(Hardware knows where this is)**



Use array of function pointers to locate OS functions  
(Hardware knows this through **lidt** instruction)

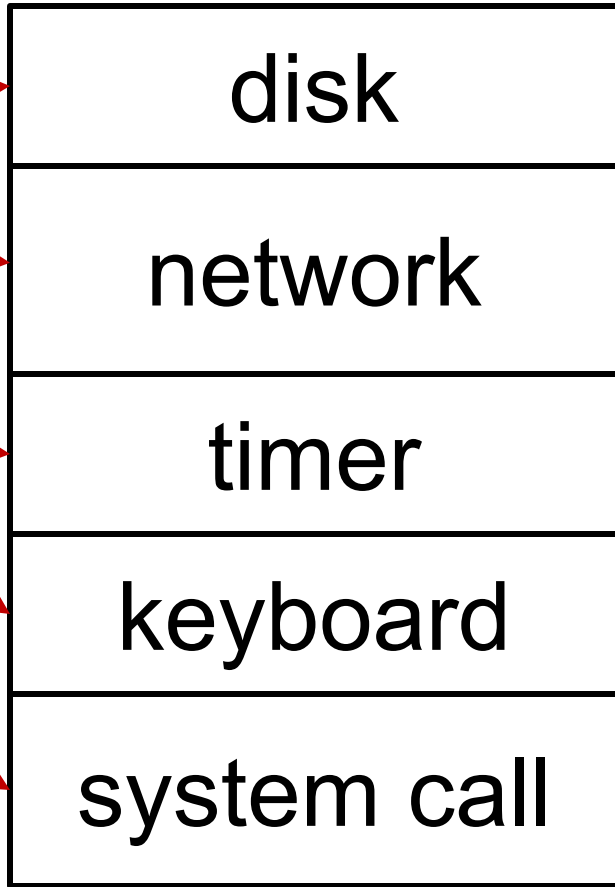
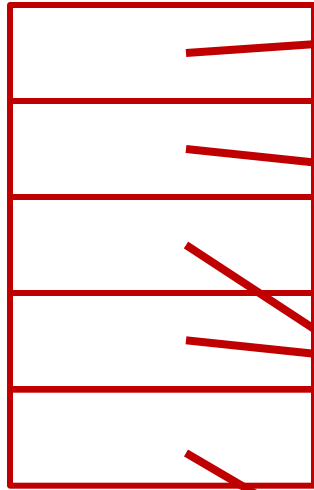
Trap table



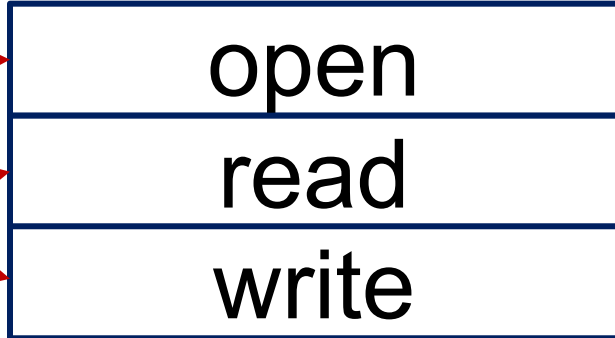
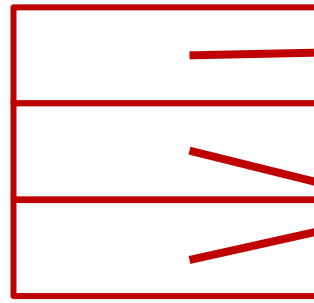
How to handle variable number of system calls?



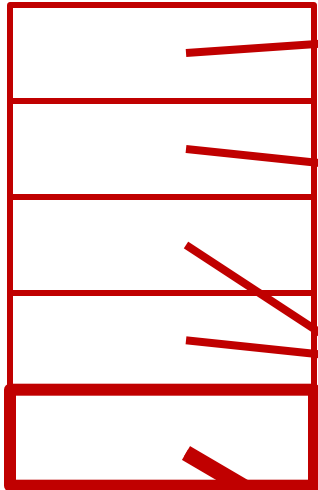
Trap table



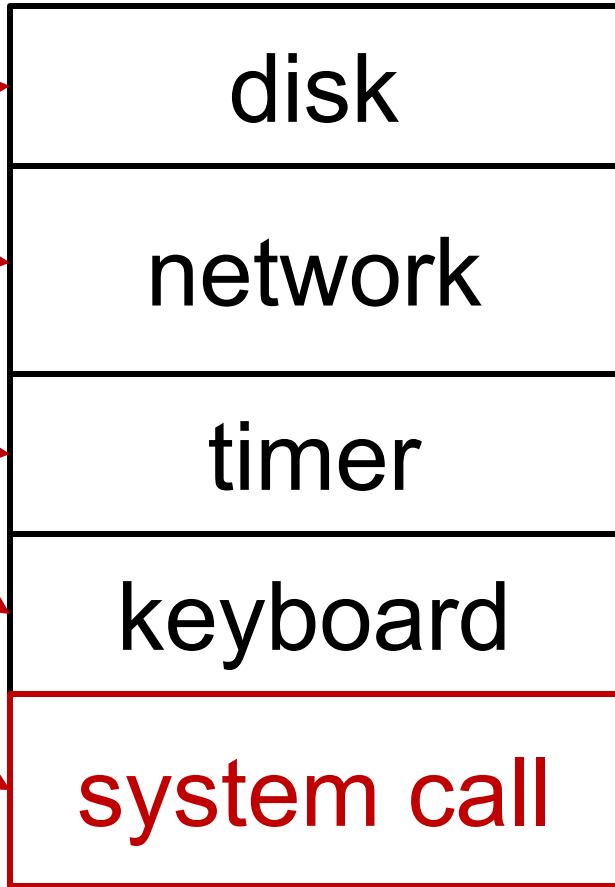
syscall table



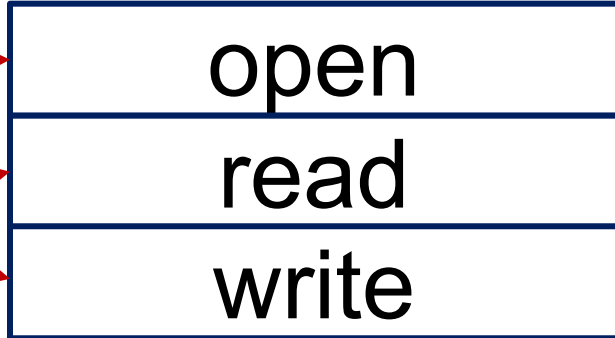
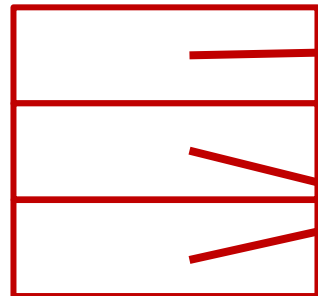
Trap table

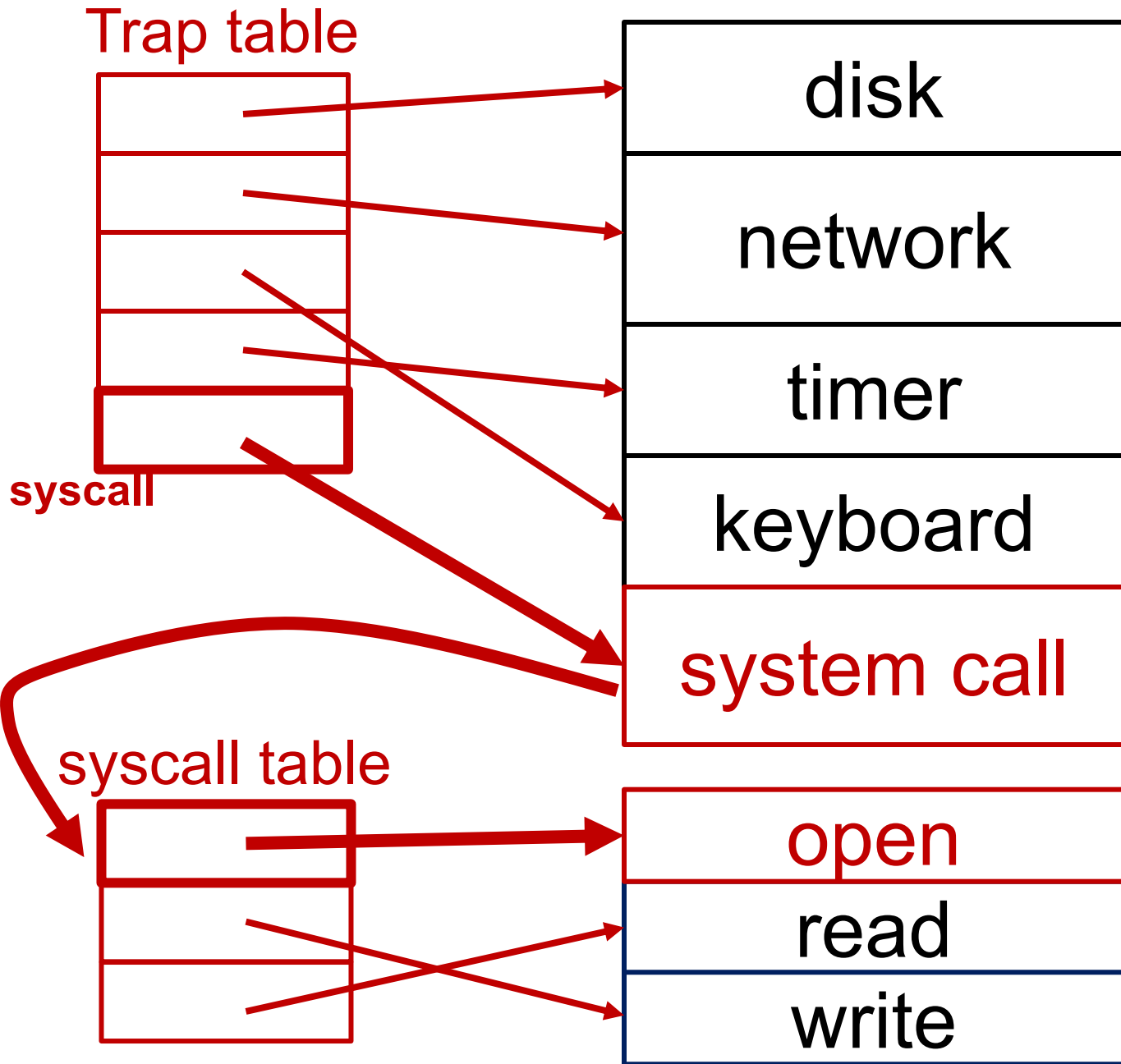


syscall



syscall table





# Safe Transfers

- Only certain kernel functions should be callable
- Privileges should escalate at the moment of the call
  - Read/write disk
  - Kill processes
  - Access all memory
  - ...

# LDE: Remaining Challenges

- ~~1. What if process wants to do something privileged?~~
- 2. How can OS switch processes (or do anything) if it's not running?**

# Sharing (virtualizing) the CPU

# How does OS share...

- CPU?
- Memory?
- Disk?

# How does OS share...

- CPU? (a: **time sharing**)
- Memory? (a: space sharing)
- Disk? (a: space sharing)



# How does OS share...

○ CPU? (a: **time sharing**)

**Today**

○ Memory? (a: space sharing)

○ Disk? (a: space sharing)

# How does OS share...

- CPU? (a: **time sharing**)

**Today**

- Memory? (a: space sharing)

- Disk? (a: space sharing)

**Goal:** processes should **not** know they are sharing  
(each process will get its own virtual CPU)

# What to do with processes that are not running?

- A: Store context in OS struct

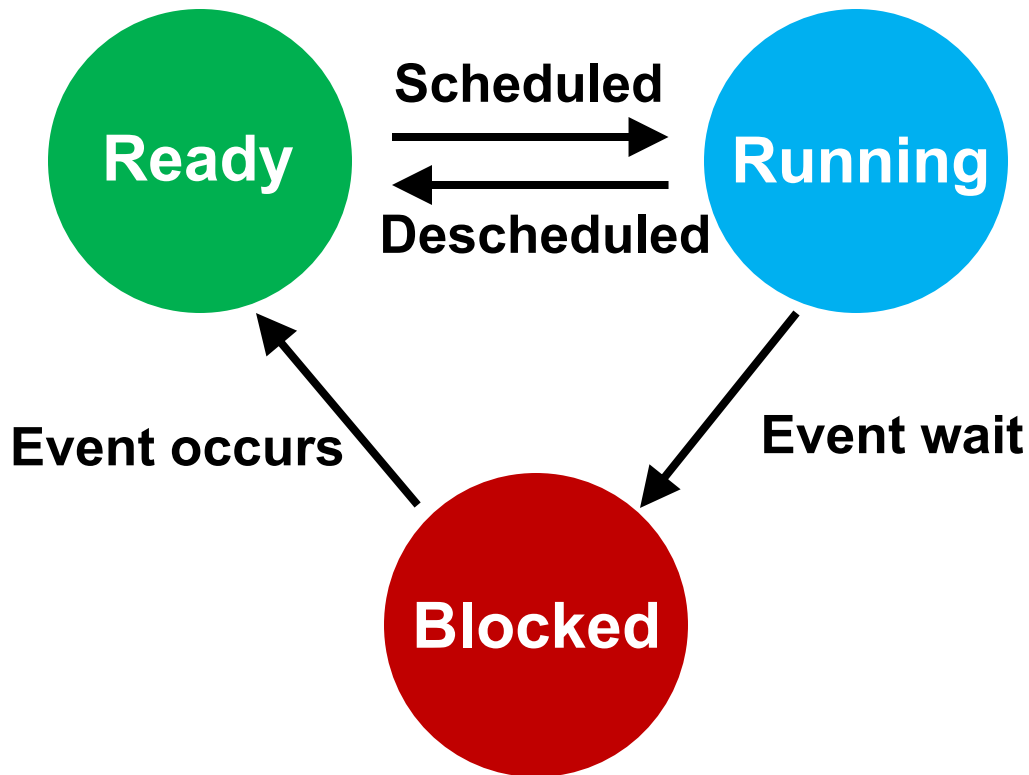
# What to do with processes that are not running?

- A: Store context in OS struct
- Context:
  - CPU registers
  - Open file descriptors
  - State (sleeping, running, etc.)

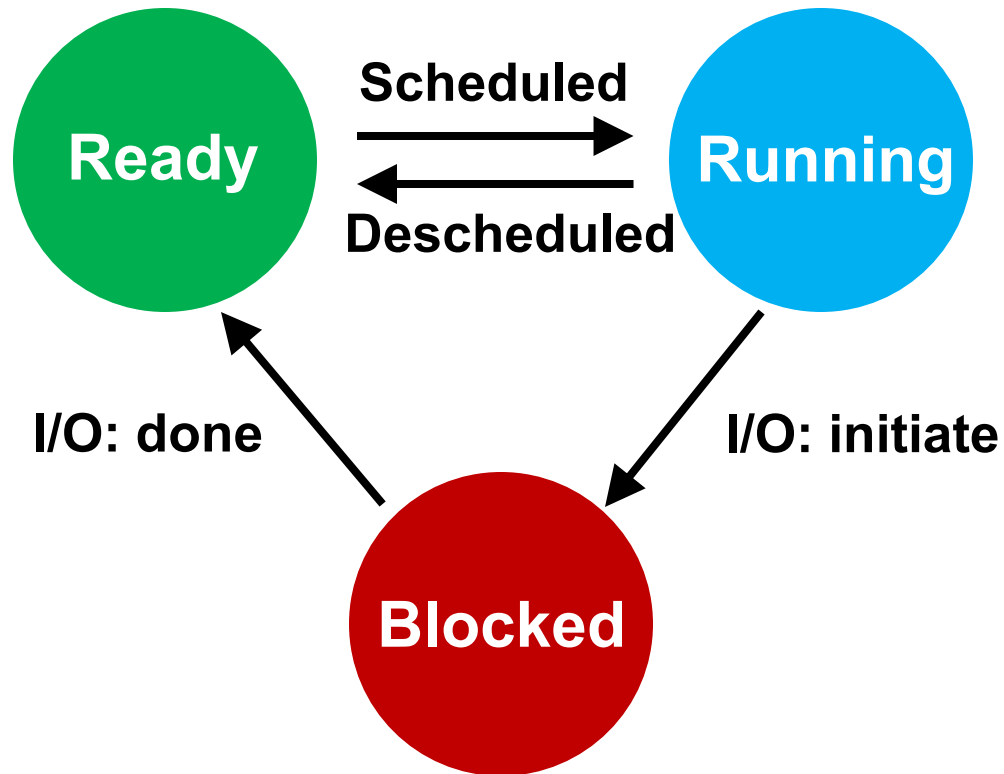
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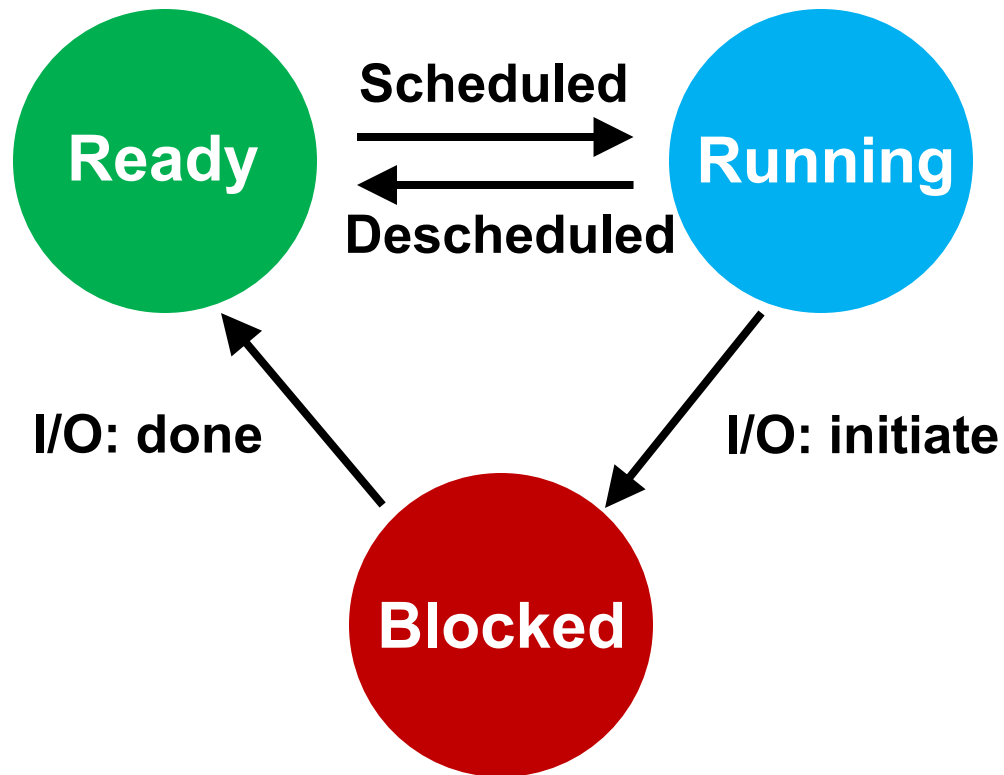
# Process State Transitions



# Process State Transitions



# Process State Transitions

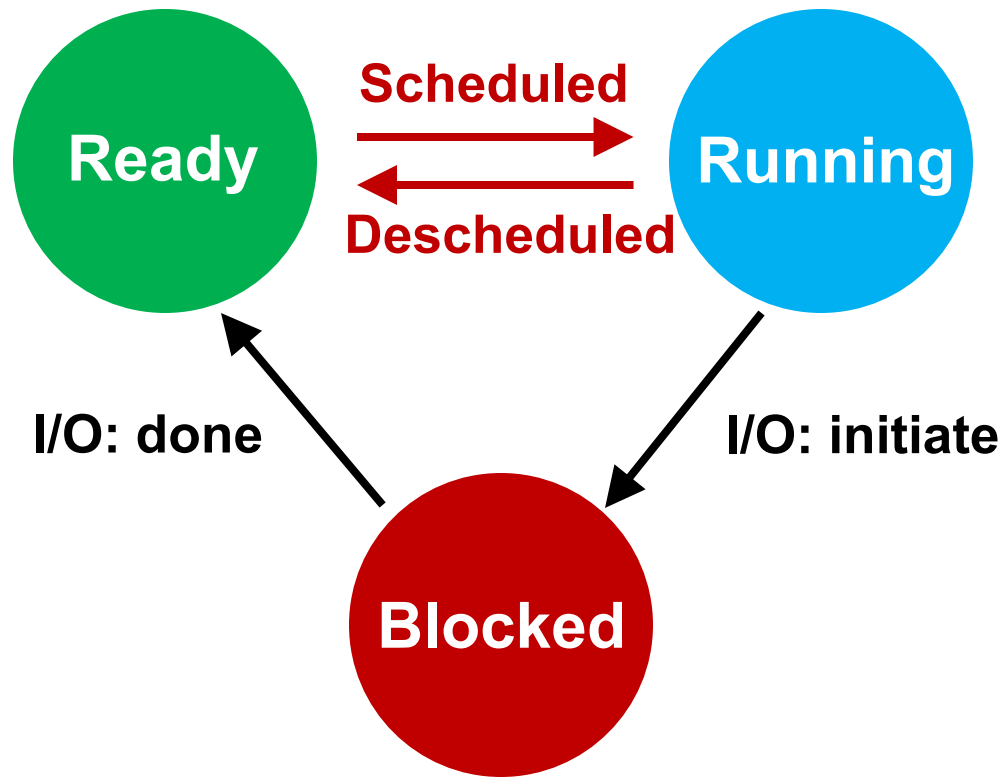


View process state with "ps xa"



# How to transition? (mechanism)

## When to transition? (policy)



# Context Switch

- Problem: When to switch process contexts?
- Direct execution => OS can't run while process runs
  
- Can OS do anything while it's not running?
- **A: it can't**

# Context Switch

- Problem: When to switch process contexts?
- Direct execution => OS can't run while process runs
  
- Can OS do anything while it's not running?
- **A: it can't**
  
- Solution: Switch on **interrupts**
  - But what interrupt?

# Cooperative Approach

- Switch contexts for syscall interrupt
  - Special `yield()` system call

# Cooperative Approach

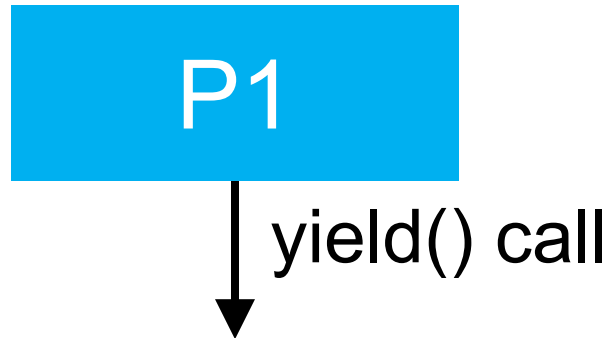
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P1

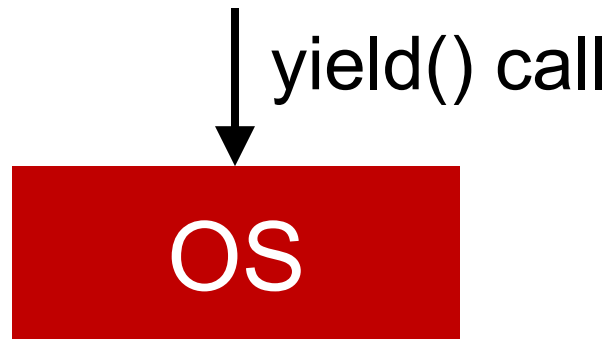
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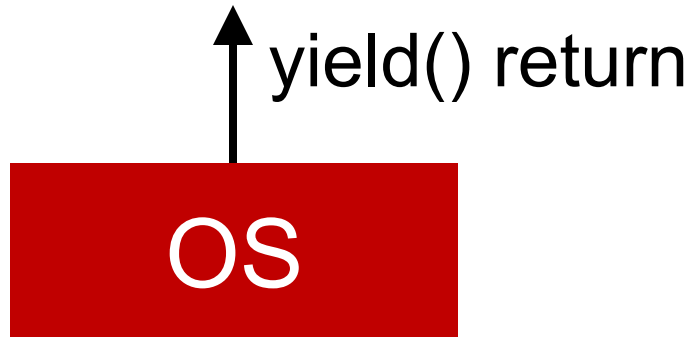


OS



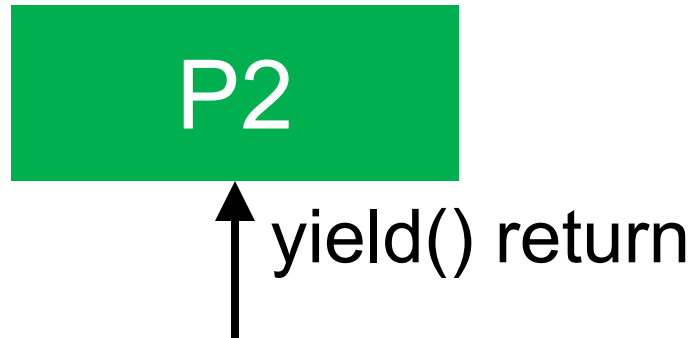
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# Cooperative Approach

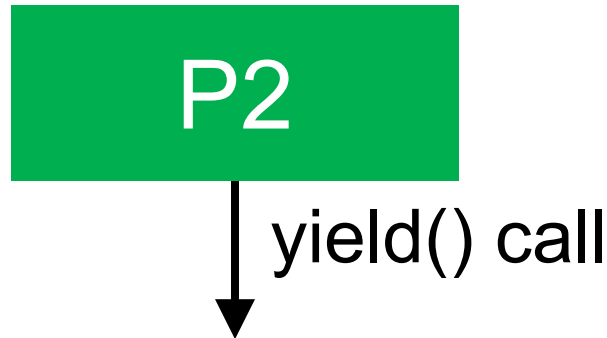
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P2

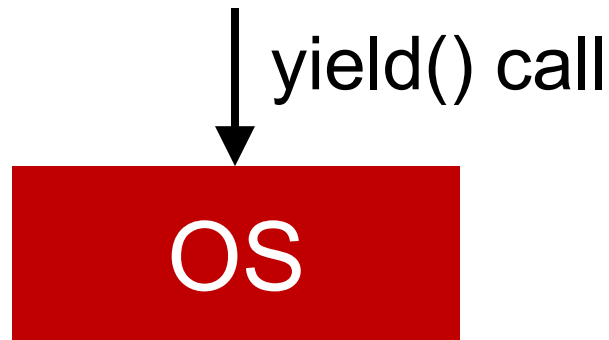
# Cooperative Approach

- Switch contexts for syscall interrupt
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# Cooperative Approach

- Switch contexts for syscall interrupt
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# Cooperative Approach

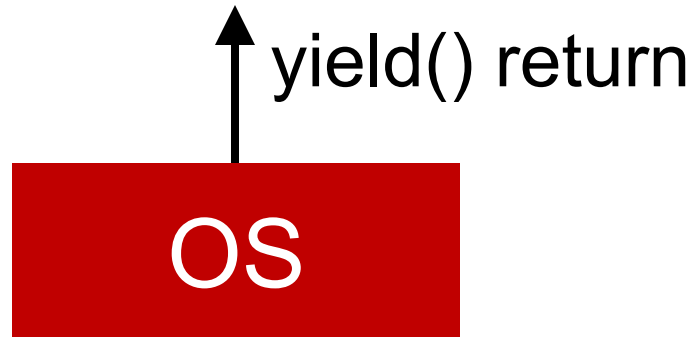
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OS

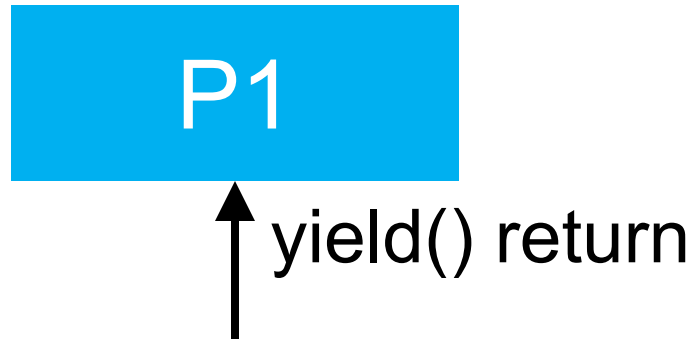
# Cooperative Approach

- Switch contexts for syscall interrupt
  - Special `yield()` system call



# Cooperative Approach

- Switch contexts for syscall interrupt
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# Cooperative Approach

- Switch contexts for syscall interrupt
  - Special `yield()` system call



P1

# Cooperative Approach

- Switch contexts for syscall interrupt
  - Special `yield()` system call



P1

**Critiques?**

# Cooperative Approach

- Switch contexts for syscall interrupt
  - Special `yield()` system call
- Cooperative approach is a **passive** approach



P1

**Critiques?**

**What if P1 never calls `yield()`?**

# Non-Cooperative Approach

- Switch contexts on **timer (hardware) interrupt**
- Set up before running any processes
- Hardware does not let processes prevent this
  - Hardware/OS enforces **process preemption**

# Non-Cooperative Approach

OS @ run  
(kernel mode)

Hardware

Program  
(user mode)

---

Process A

...

# Non-Cooperative Approach

OS @ run  
(kernel mode)

Hardware

Program  
(user mode)

---

Process A

...

**timer interrupt**

save regs(A) to k-stack(A)

move to kernel mode

jump to trap handler

# Non-Cooperative Approach

OS @ run  
(kernel mode)

Hardware

Program  
(user mode)

Process A

...

**timer interrupt**

save regs(A) to k-stack(A)

move to kernel mode

jump to trap handler

Handle the trap

Call `switch()` routine

save regs(A) to `proc-struct(A)`

restore regs(B) from `proc-struct(B)`

switch to `k-stack(B)`

**return-from-trap (into B)**

# Non-Cooperative Approach

OS @ run  
(kernel mode)

Hardware

Program  
(user mode)

Process A

...

**timer interrupt**

save regs(A) to k-stack(A)

move to kernel mode

jump to trap handler

Handle the trap

Call `switch()` routine

save regs(A) to proc-struct(A)

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restore regs(B) from k-stack(B)

move to user mode

jump to B's PC



# Non-Cooperative Approach

OS @ run  
(kernel mode)

Hardware

Program  
(user mode)

Process A

...

**timer interrupt**

save regs(A) to k-stack(A)

move to kernel mode

jump to trap handler

Handle the trap

Call `switch()` routine

save regs(A) to proc-struct(A)

restore regs(B) from proc-struct(B)

switch to k-stack(B)

**return-from-trap (into B)**

restore regs(B) from k-stack(B)

move to user mode

jump to B's PC

Process B

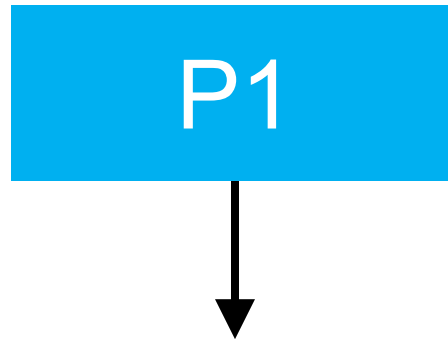
...

# Preemptive Approach



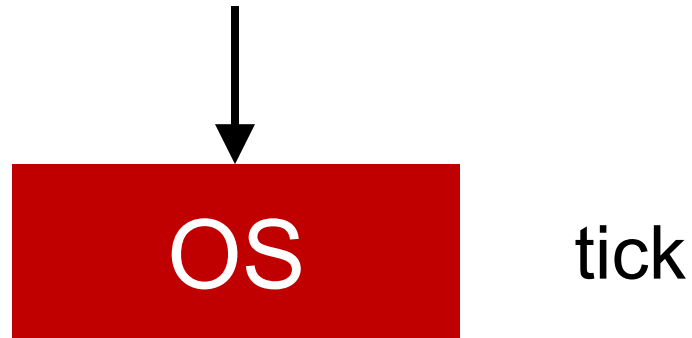
P1

# Preemptive Approach



tick

# Preemptive Approach

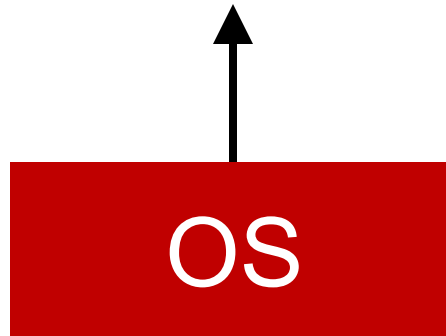


# Preemptive Approach

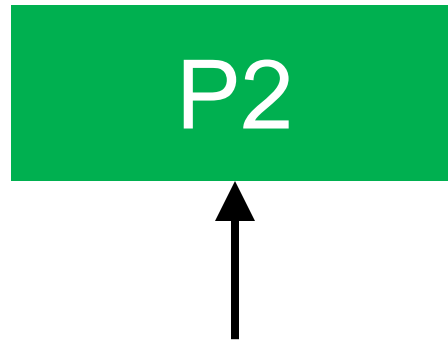


OS

# Preemptive Approach



# Preemptive Approach



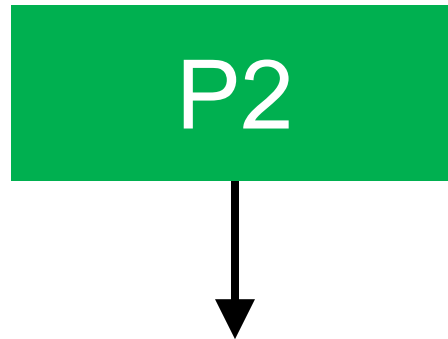
# Preemptive Approach



P2

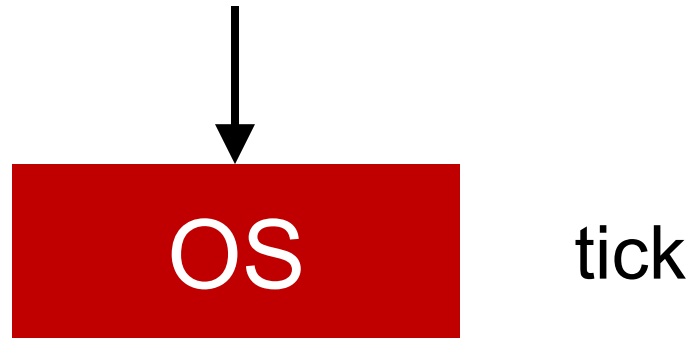


# Preemptive Approach



tick

# Preemptive Approach

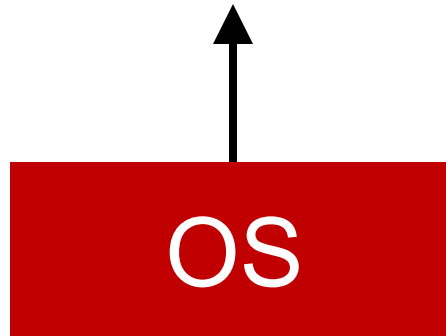


# Preemptive Approach

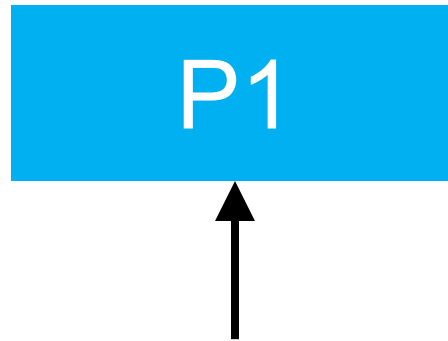


OS

# Preemptive Approach



# Preemptive Approach



# Preemptive Approach



P1

# Summary

- Smooth **context switching** makes each process think it has its own CPU (virtualization!)
- **Limited direct execution** makes processes fast
- Hardware provides a lot of OS support
  - Limited direct execution
  - Timer interrupt
  - Automatic register saving